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Distributed Gaussian Processes for Large-Scale Probabilistic Regression

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Joint work with Jun Wei Ng

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Scaling Gaussian Processes to Large Data Sets

Two orthogonal approaches

- Sparse Gaussian processes
 Use (smart) subset of data.
- Distributed Gaussian processes
 - ▶ Use full data set, distribute computations

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- Practical limit of the data set size is $N \in \mathcal{O}(10^6)$







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- Block-diagonal approximation of kernel matrix *K* (sim. to PIC)
- Combine independent computations to an overall result

Training the Distributed GP

- Randomly split data set of size *N* into *M* chunks of size *P*
- ▶ Independence of experts ▶ Factorization of marginal likelihood:

$$\log p(\boldsymbol{y}|\boldsymbol{X},\boldsymbol{\theta}) \approx \sum_{k=1}^{M} \log p_k(\boldsymbol{y}^{(k)}|\boldsymbol{X}^{(k)},\boldsymbol{\theta})$$

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- Distributed optimization and training straightforward
- ▸ No inducing/variational parameters ➤ Easy optimization
- Computational complexity: $\mathcal{O}(MP^3)$ [instead of $\mathcal{O}(N^3)$]
- Memory footprint: $\mathcal{O}(MP^2 + ND)$ [instead of $\mathcal{O}(N^2 + ND)$], potentially distributed across *M* computing nodes

Scaling



- NLML is proportional to training time
- Full GP (16K training points) ≈ sparse GP (32K training points)
 ≈ distributed GP (16M training points)

▶ Push practical limit by order(s) of magnitude

Distributed Gaussian Processes

Predictions with the Distributed GP



- Prediction of each GP expert is Gaussian $\mathcal{N}(\mu_i, \sigma_i^2)$
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- Product-of-GP-experts
 - ▶ PoE (product of experts) ▶ (Ng & Deisenroth, 2014)
 - ▶ gPoE (generalized product of experts) ▶ (Cao & Fleet, 2014)
 - ▶ BCM (Bayesian Committee Machine) ▶ (Tresp, 2000)
 - rBCM (robust BCM)
 ▶ (Deisenroth & Ng, 2015)

Scale to large data sets ✓

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- Good approximation of full GP ("ground truth")



Figure: Two computational graphs

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- Predictions independent of computational graph
 Heterogeneous computing infrastructures (laptop, cluster, ...)



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- Good approximation of full GP ("ground truth")
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 Heterogeneous computing infrastructures (laptop, cluster, ...)
- Reasonable predictive variances

Running Example



Investigate various product-of-experts models
 Same training procedure, but different mechanisms for predictions

Product of GP Experts

Prediction model (independent predictors):

$$p(f_*|\mathbf{x}_*, \mathcal{D}) = \prod_{k=1}^M p_k(f_*|\mathbf{x}_*, \mathcal{D}^{(k)}),$$
$$p_k(f_*|\mathbf{x}_*, \mathcal{D}^{(k)}) = \mathcal{N}(f_* | \mu_k(\mathbf{x}_*), \sigma_k^2(\mathbf{x}_*))$$

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▶ Independent of computational graph ✓

Product of GP Experts



• Unreasonable variances for *M* > 1:

$$(\sigma_*^{\text{poe}})^{-2} = \sum_k \sigma_k^{-2}(x_*)$$

 The more experts the more certain the prediction, even if every expert itself is very uncertain ✗ ➡ Cannot fall back to the prior

Distributed Gaussian Processes

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With ∑_k β_k = 1, the model can fall back to the prior ✓
 ▶ Log-opinion pool model (e.g., Heskes, 1998)



Prediction:

$$p(f_*|\mathbf{x}_*, \mathcal{D}) = \prod_{k=1}^M p_k^{\beta_k}(f_*|\mathbf{x}_*, \mathcal{D}^{(k)}) = \prod_{k=1}^L \prod_{i=1}^{L_k} p_{k_i}^{\beta_{k_i}}(f_*|\mathcal{D}^{(k_i)}), \quad \sum_{k,i} \beta_{k_i} = 1$$



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• Independent of computational graph if $\sum_{k,i} \beta_{k_i} = 1 \checkmark$



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- Independent of computational graph if $\sum_{k,i} \beta_{k_i} = 1 \checkmark$
- A priori setting of β_{k_i} required **X**
 - $\blacktriangleright \beta_{k_i} = 1/M \text{ a priori} (\checkmark)$

Generalized Product of GP Experts



- Same mean as PoE
- Model no longer overconfident and falls back to prior \checkmark
- Very conservative variances X

Distributed Gaussian Processes

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$$(\sigma_*^{\text{bcm}})^{-2} = \sum_{k=1}^M \sigma_k^{-2}(\mathbf{x}_*) - (M-1)\sigma_{**}^{-2}$$
$$\mu_*^{\text{bcm}} = (\sigma_*^{\text{bcm}})^2 \sum_{k=1}^M \sigma_k^{-2}(\mathbf{x}_*)\mu_k(\mathbf{x}_*)$$

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- Product of GP experts, divided by M 1 times the prior
- Guaranteed to fall back to the prior outside data regime \checkmark



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► Independent of computational graph ✓

Bayesian Committee Machine



- Independent of computational graph \checkmark
- Variance estimates are about right \checkmark
- When leaving the data regime, the BCM can produce junk X

▶ Robustify

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• Predictive precision and mean:

$$(\sigma_*^{\rm rbcm})^{-2} = \sum_{k=1}^M \beta_k \sigma_k^{-2}(\mathbf{x}_*) + (1 - \sum_{k=1}^M \beta_k) \sigma_{**}^{-2} ,$$

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▶ Independent of computational graph, even with arbitrary $\beta_k \checkmark$



- Does not break down in case of weak experts ➤ Robustified ✓
- Robust version of BCM ➡ Reasonable predictions ✓
- Independent of computational graph (for all choices of β_k) \checkmark

Distributed Gaussian Processes

Empirical Approximation Error



- Simulated robot arm data (10K training, 30K test)
- · All models use hyper-parameters of ground-truth full GP
- RMSE as a function of the training time
- Sparse GP (SOD) performs worse than any distributed GP
- rBCM performs best with "weak" GP experts

Distributed Gaussian Processes

Empirical Approximation Error (2)



- ▶ NLPD as a function of the training time ▶ Mean and variance
- BCM and PoE are not robust to weak experts
- gPoE suffers from too conservative variances
- rBCM consistently outperforms other methods

Distributed Gaussian Processes

Large Data

- Predict US Airline Delays (01/2008–04/2008) of commercial flights
- Inputs: age of aircraft, flight distance, departure/arrival time, airtime, day of week, day of month, month,
- Training data: 700K, 2M, 5M. Test data: 100K

Training Data: 700K — RMSE



- (r)BCM and (g)PoE with 4096 GP experts
- Gradient time: 13 seconds (12 cores)
- Inducing inputs: Dist-VGP (Gal et al., 2014), SVI-GP (Hensman et al., 2013)

- rBCM performs best
- ▶ (g)PoE and BCM performs not worse sparse GPs

Training Data: 700K — NLPD



- (r)BCM and (g)PoE with 4096 GP experts
- Gradient time: 13 seconds (12 cores)
- No results reported for inducing input methods (Gal et al., 2014; Hensman et al., 2013)
- gPoE performs best, just ahead of rBCM

Training Data: 2M — RMSE



- (r)BCM and (g)PoE with 8192 GP experts
- Gradient time: 39 seconds (12 cores)
- Inducing inputs: Dist-VGP (Gal et al., 2014)

- rBCM performs best
- (g)PoE as good as best results reported for sparse methods
- BCM suffers from weak experts

Distributed Gaussian Processes

Training Data: 2M — NLPD



- (r)BCM and (g)PoE with 8192 GP experts
- Gradient time: 39 sec (12 cores)
- Inducing inputs: no results reported

- rBCM and gPoE perform best
- BCM suffers from weak experts
- PoE suffers from under-estimation of variances

Training Data: 5M — RMSE



- rBCM performs best
- (g)PoE produce good results
- BCM off the chart ▶ suffers from weak experts

Training Data: 5M — NLPD



- (r)BCM and (g)PoE with 32768 GP experts
- Gradient time: 90 sec (12 cores)

- rBCM and gPoE perform best
- PoE and BCM significantly worse

Overview Airline Delays

- RMSE: rBCM consistently performs best
- NLPD: rBCM and gPoE approximately the same
 gPoE recovers because of conservative variance estimates
- BCM suffers from "wrong means", PoE suffers from overconfident estimates
- All models: Training time is acceptable
- All experiments (DGP) run on a laptop

Summary

- Distributed product-of-experts approaches to scaling Gaussian processes to large data sets
- Robust Bayesian Committee Machine
- Model conceptually straightforward and easy to train
 Only kernel hyper-parameters need to be optimized
- Independent of computational graph
- Scales to arbitrarily large data sets (in principle)

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Thank you for your attention

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