

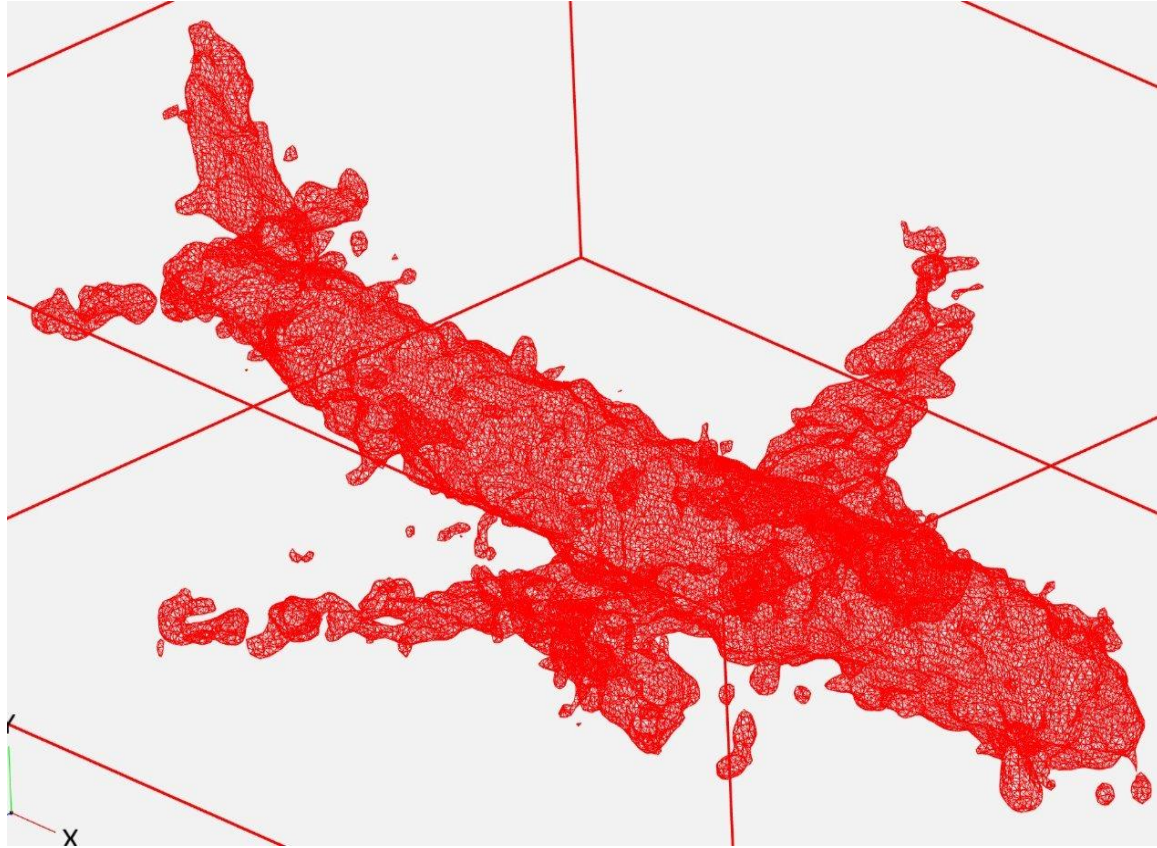
Experimental Design in the Age of Generative AI

Henry Moss

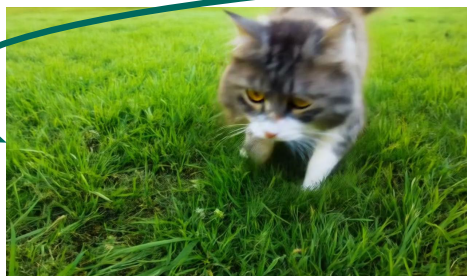
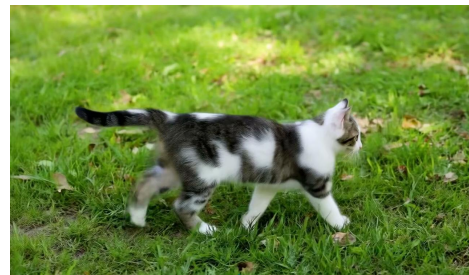
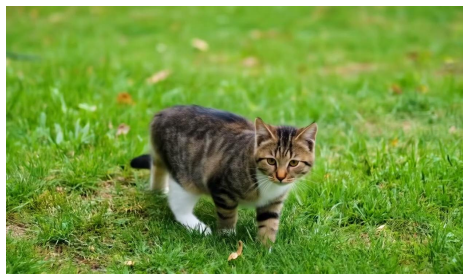
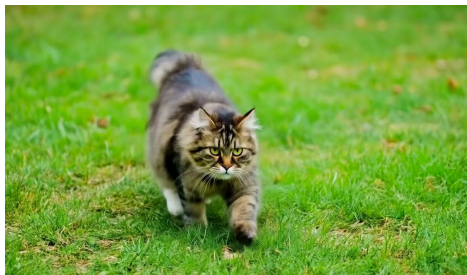


DO INTERRUPT ME PLS





Start Video



End Video



Bayesian Optimisation

Bayesian Optimisation Recap

Goal:


$$\mathbf{x}^* = \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} f(\mathbf{x})$$

Search Space

Bayesian Optimisation Recap


Goal:

$$\mathbf{x}^* = \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} f(\mathbf{x})$$

 Search Space

N^{th} step:

$$\mathbf{x}_N = \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \alpha_N(\mathbf{x})$$

 Acquisition Function

Bayesian Optimisation Recap

Goal: $\mathbf{x}^* = \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} f(\mathbf{x})$

\mathcal{X} Search Space

N^{th} step: $\mathbf{x}_N = \operatorname{argmax}_{\mathbf{x} \in \mathcal{X}} \mathbf{P}(\tilde{f}(\mathbf{x}) > f^* | D_N)$

Acquisition Optimizer

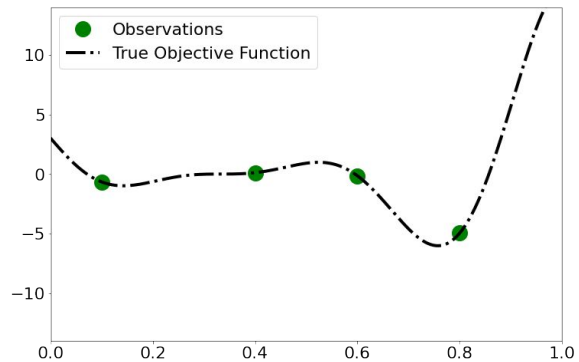
Acquisition Function

Surrogate model



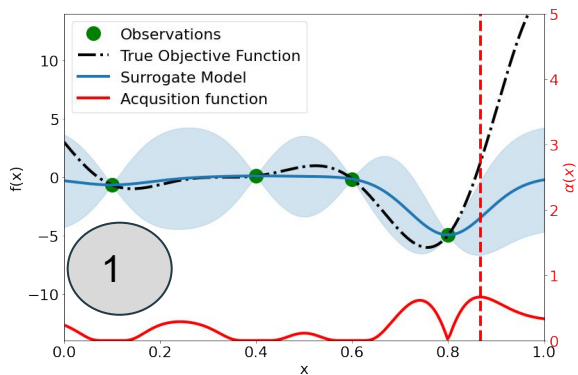
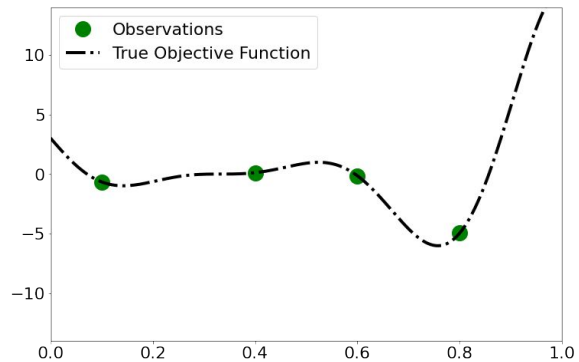
Expected Improvement

Demo BO loop



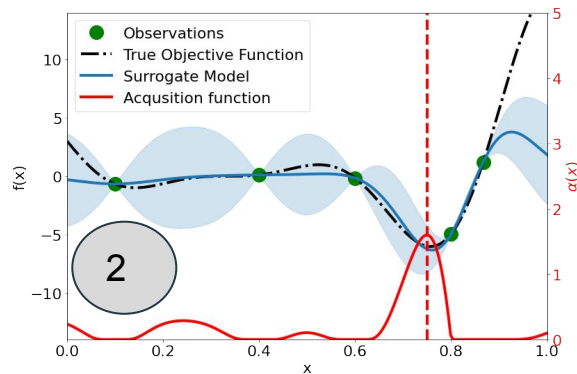
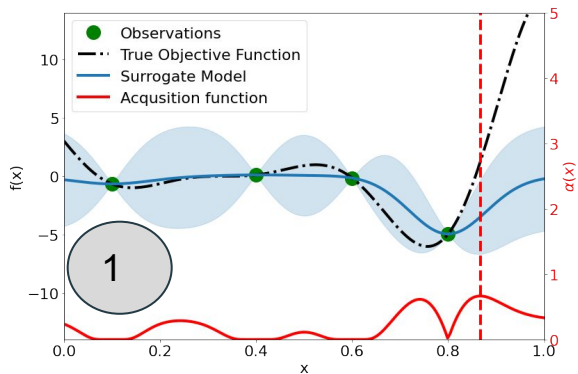
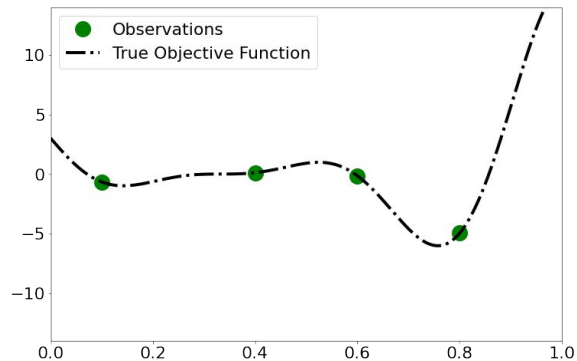
Expected Improvement

Demo BO loop



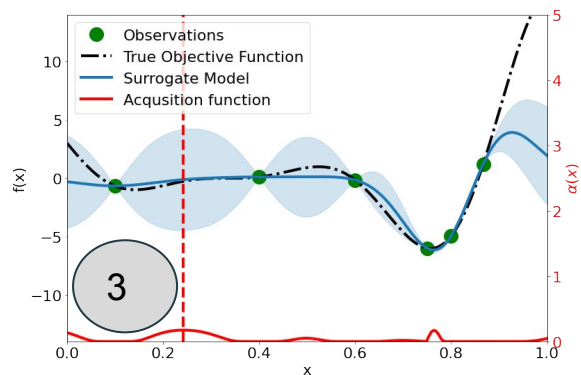
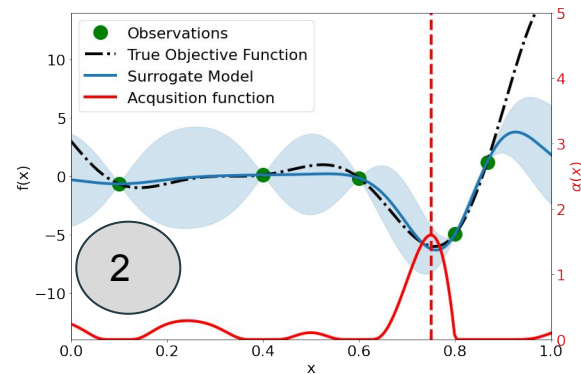
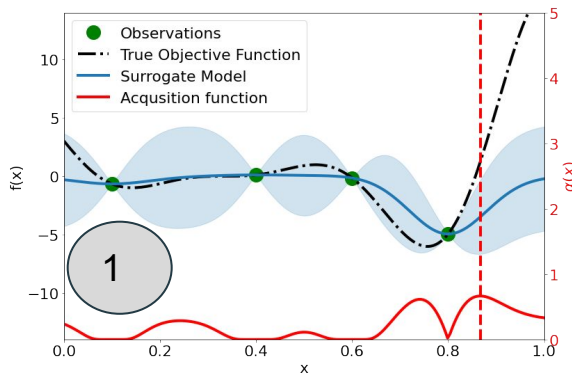
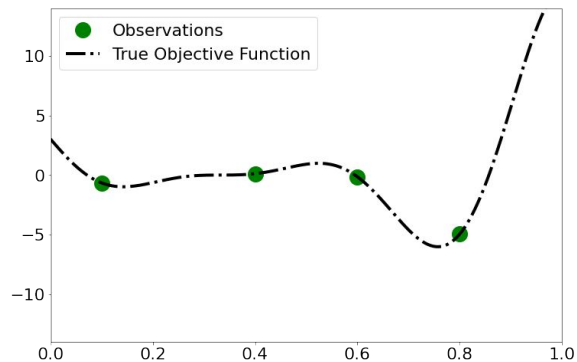
Expected Improvement

Demo BO loop



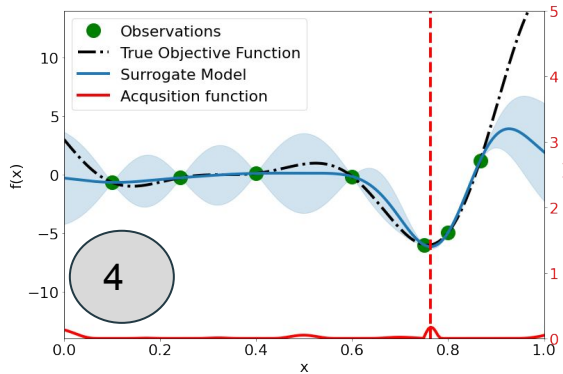
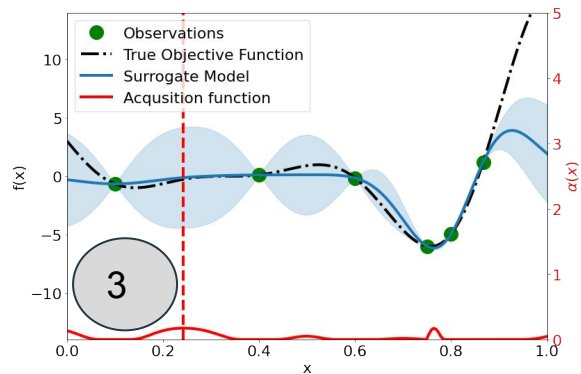
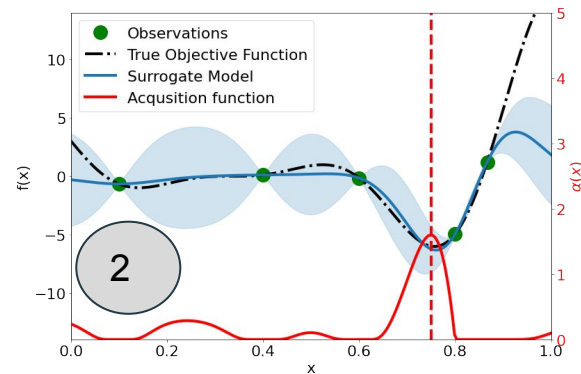
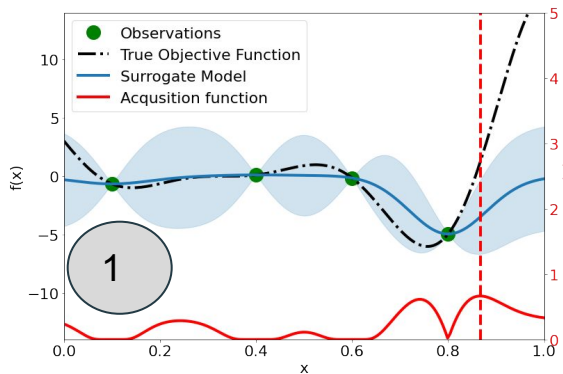
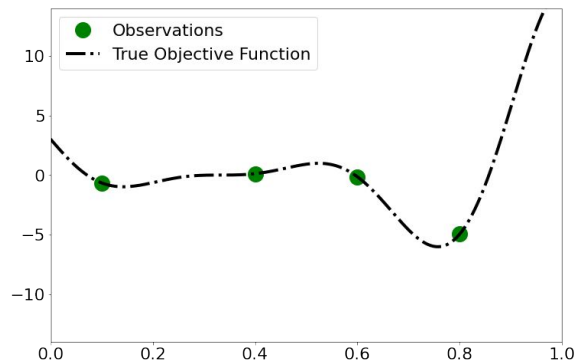
Expected Improvement

Demo BO loop



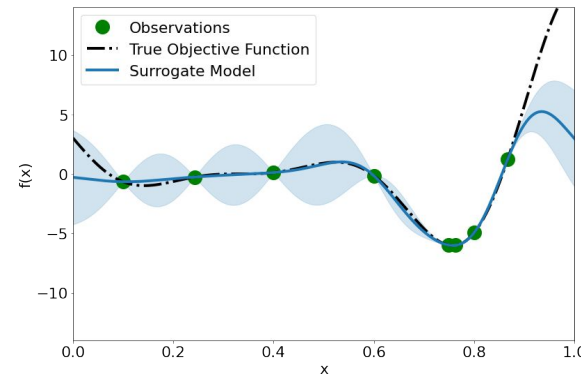
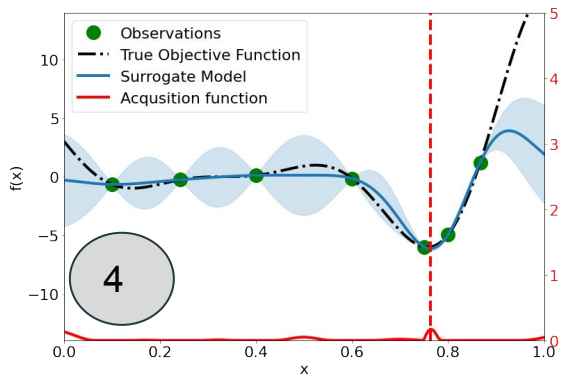
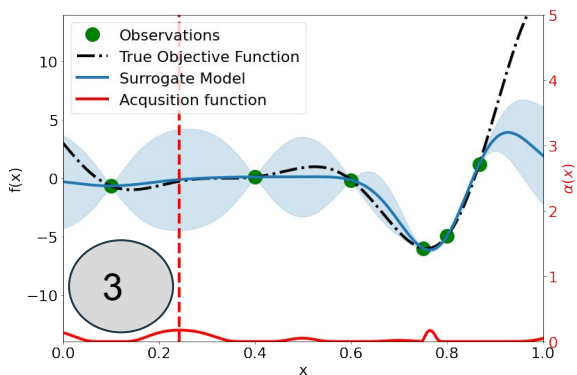
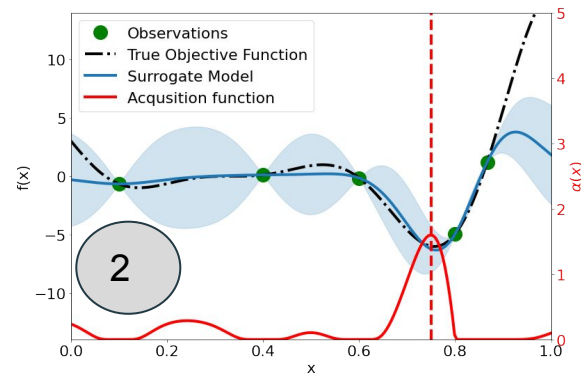
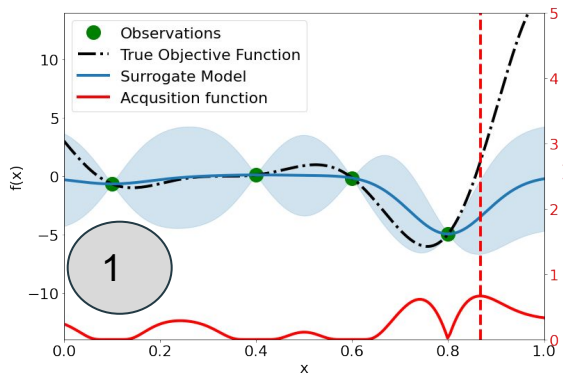
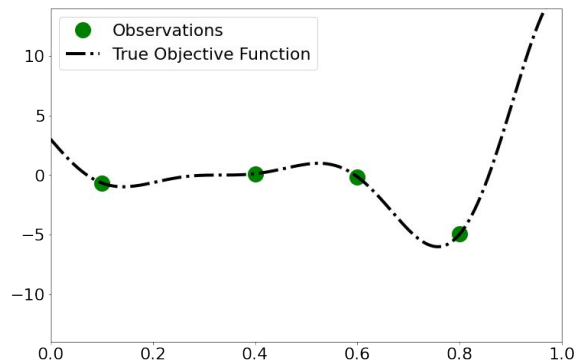
Expected Improvement

Demo BO loop

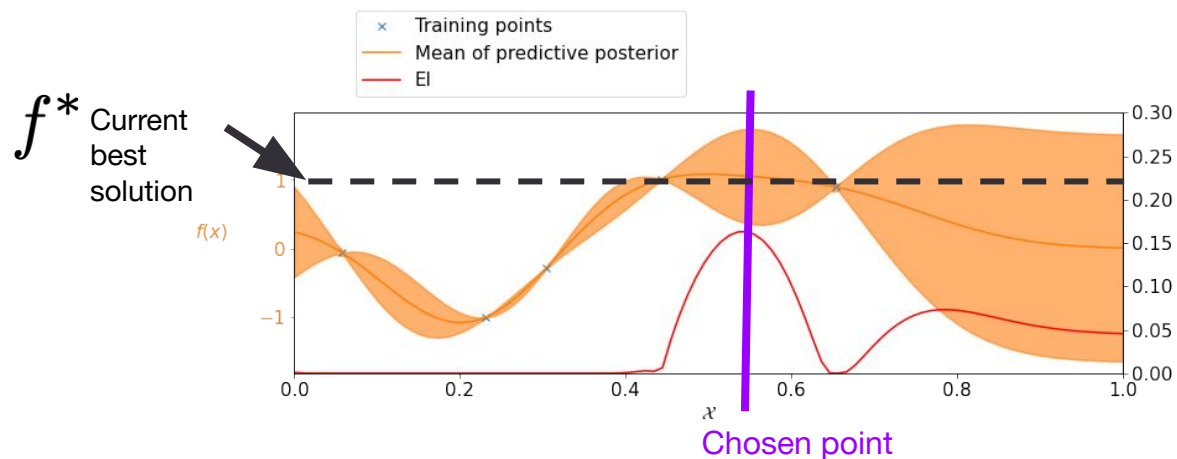


Expected Improvement

Demo BO loop



Bayesian Optimisation over Euclidean space



- Search Space: $\mathcal{X} \subset \mathbb{R}^d$
- Surrogate Model: $\tilde{f} \sim \mathcal{GP}(0, k_{\text{RBF}})$
- Acquisition optimiser: cts (+gradients)



Bayesian Optimisation of “structured” spaces



Bayesian Optimisation over Categories



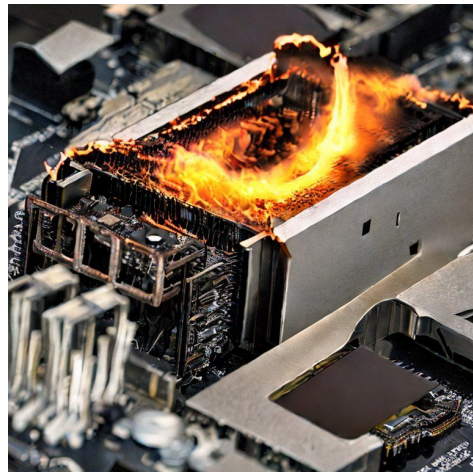
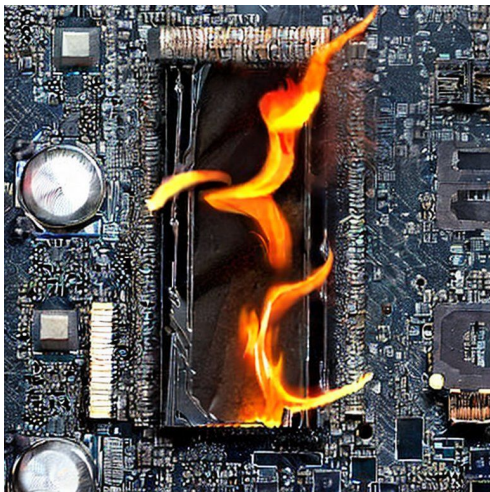
- Search Space: $\mathcal{X} = \{0, 1\}^d$
- Surrogate Model: $\tilde{f}(\mathbf{x}) = \alpha_0 + \sum \alpha_j x_j + \sum \alpha_{ij} x_i x_j$
- Acquisition optimiser: binary quadratic programming

Bayesian Optimisation over Mixed Spaces



- Search Space: $\mathcal{X} = \mathbb{R}^{d_1} \cup \{0, 1\}^{d_2}$
- Surrogate Model: $\tilde{f} \sim \mathcal{GP}(0, k_{\text{diffusion}})$
- Acquisition optimiser: Alternating cts + discrete

Bayesian Optimisation over Permutations



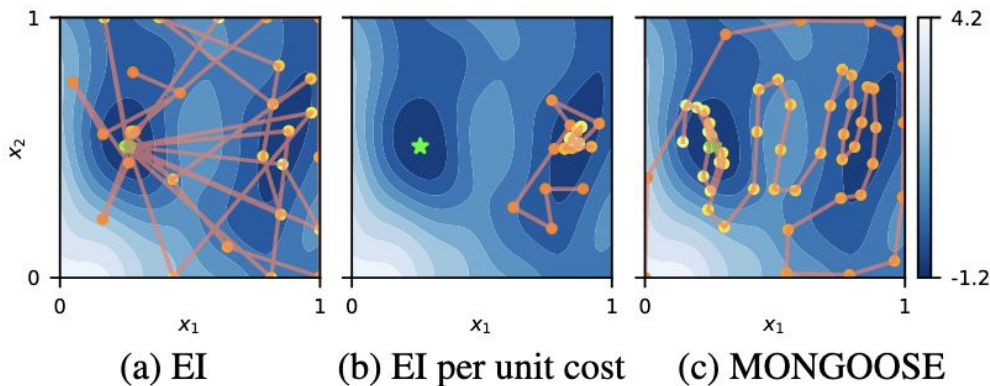
- Search Space: $\mathcal{X} = S_d$
- Surrogate Model: $\tilde{f} \sim \mathcal{GP}(0, k_{\text{Mallow}})$
- Acquisition optimiser: Evolutionary optimiser

String Bayesian Optimisation

1. **Unconstrained** Any string made exclusively from characters in the alphabet Σ are allowed. S contains all these strings of any (or a fixed) length.
2. **Locally constrained** S is a collection of strings of fixed length, where the set of possible values for each character depends on its position in the string, i.e. the character s_i at location i belongs to the set $\Sigma_i \subseteq \Sigma$.
3. **Grammar constrained** S is the set of strings made from Σ that satisfy the syntactical rules specified by a context-free grammar.
4. **Candidate Set.** A space with unknown or very complex syntactical rules, but for which we have access to a large collection S of valid strings.

- Search Space: $\mathcal{X} = \mathcal{S}$
- Surrogate Model: $\tilde{f} \sim \mathcal{GP}(0, k_{\text{SSK}})$
- Acquisition optimiser: Genetic algorithms

Bayesian Optimisation over Paths



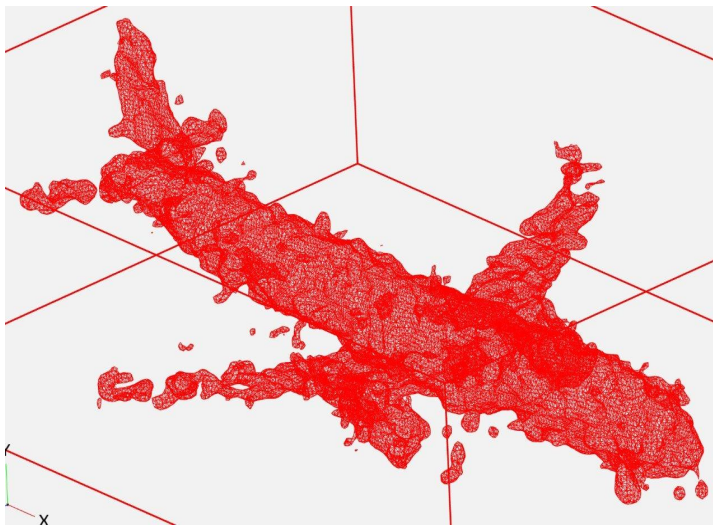
- Search Space: $\mathcal{X} = \{\text{smooth paths} \in \mathbb{R}^d\}$
- Surrogate Model: $\tilde{f} \sim \mathcal{GP}(0, k_{\text{RBF}})$
- Acquisition optimiser: Travelling Salesman / RL



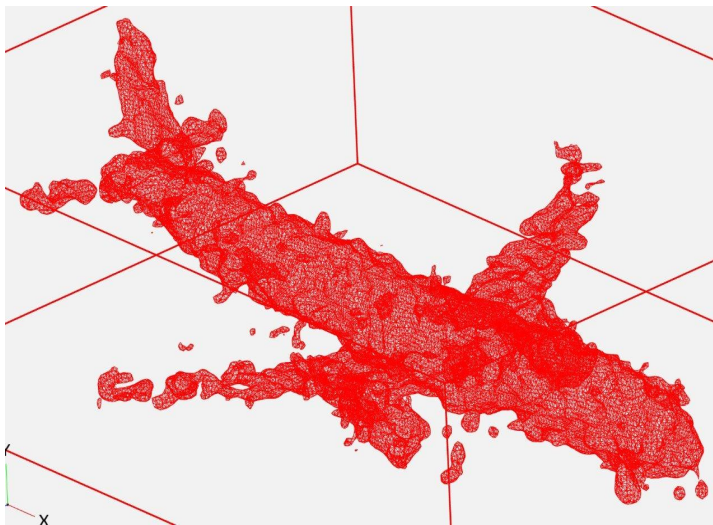
Bayesian Optimisation of “highly structured” spaces



You know it when you see it

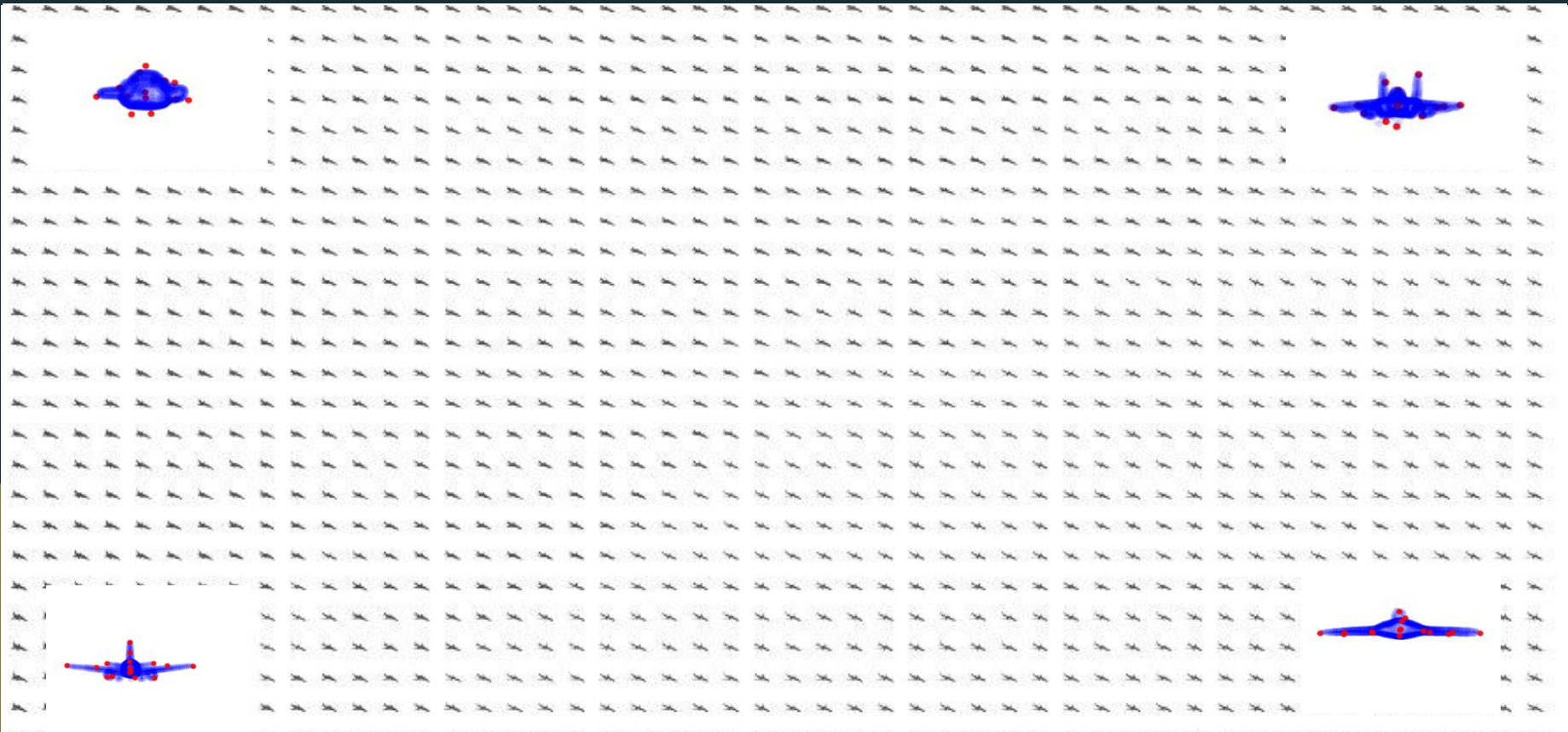


You know it when you see it



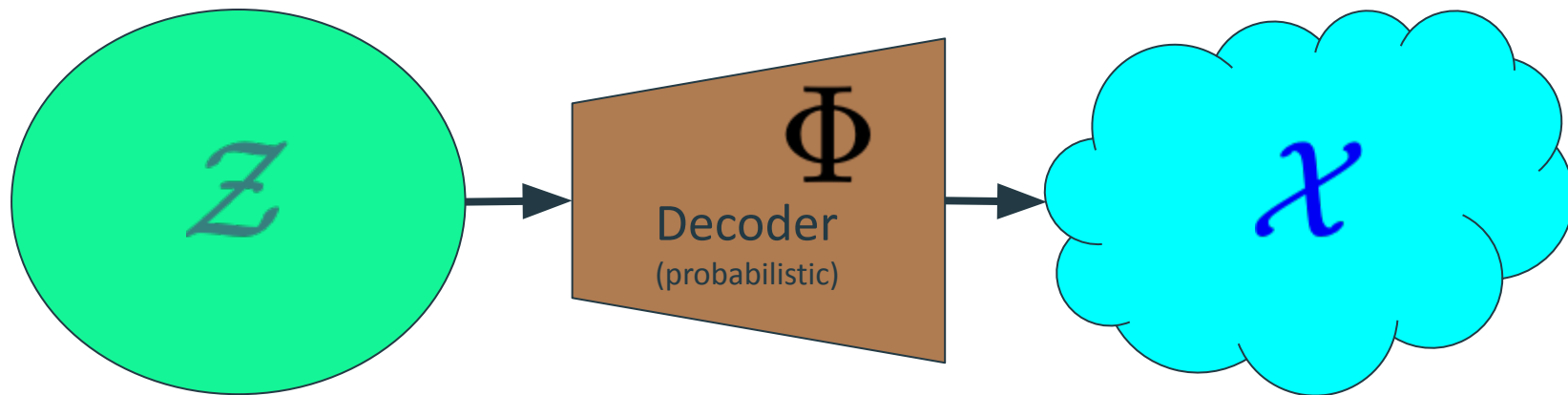
You know it when you see it

- Vanishingly small support
- Can't learn *is_plane* function



Generative AI is cool right?

Priors over “Highly Structured” spaces

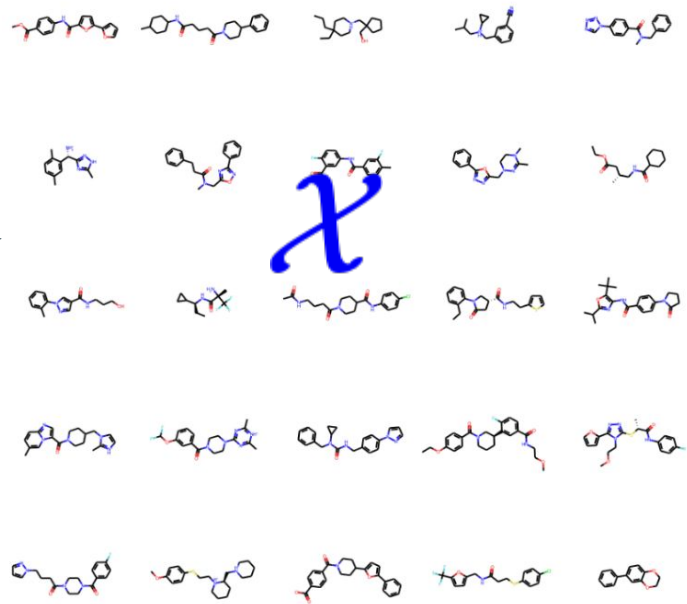
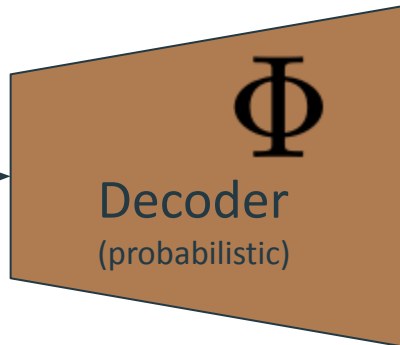
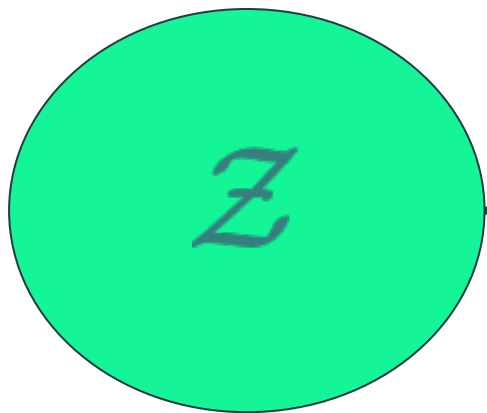


$$\mathbb{P}(\mathbf{z}) = \mathcal{N}_d(\mathbf{0}, I_d)$$

$$\mathbb{P}(\mathbf{x}) = ???$$

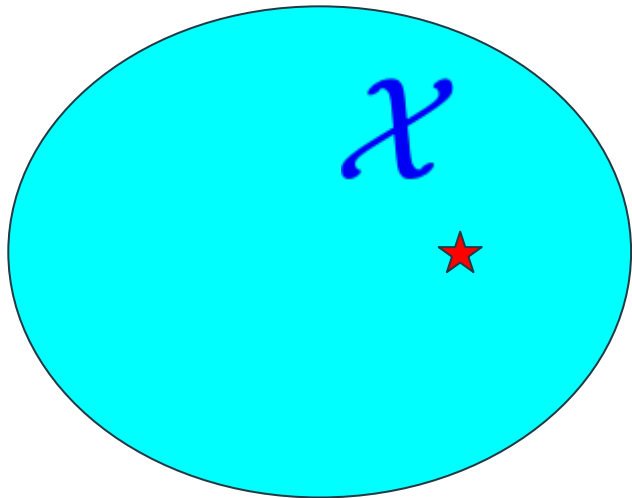
VAE / Diffusion / Normalising Flows e.t.c on unlabeled data

Priors over “Highly Structured” molecule spaces



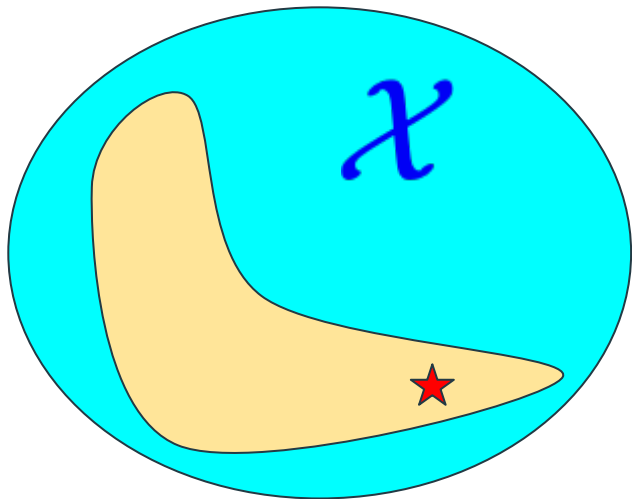
$$\mathbb{P}(\mathbf{z}) = \mathcal{N}_d(\mathbf{0}, I_d)$$

Standard BO



$$\max_{x \in \mathcal{X}} f(x)$$

Standard BO

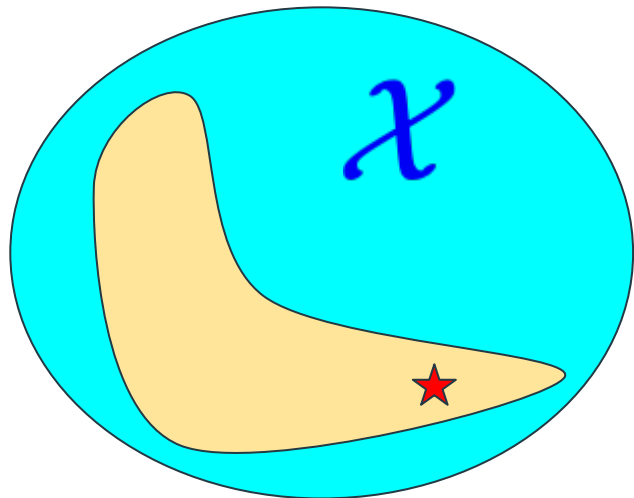


$$\begin{aligned} \max_{x \in \mathcal{X}} f(x) \\ : P(C(x) = 0) > t \end{aligned}$$

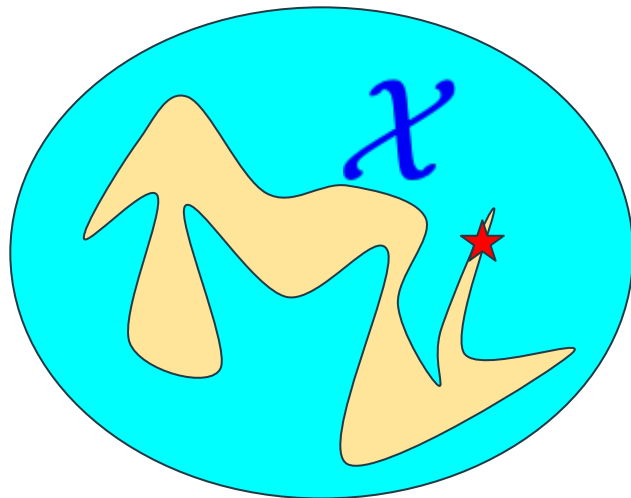
Standard BO

v.s.

BO with GenAI prior



$$\max_{x \in \mathcal{X}} f(x) \\ : P(C(x) = 0) > t$$

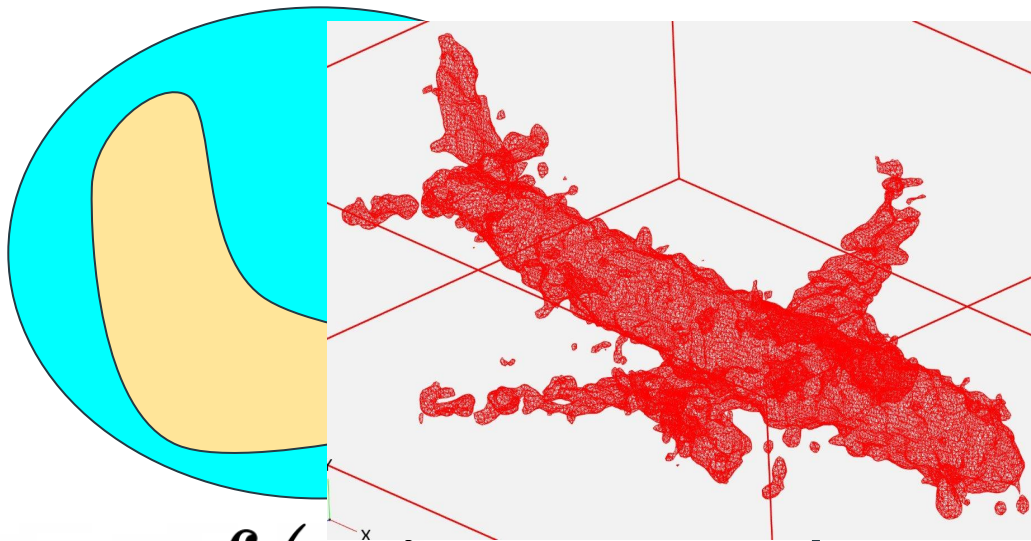


$$\max_{x \in \mathcal{X}} f(x) \\ : P(\dot{x}) > t$$

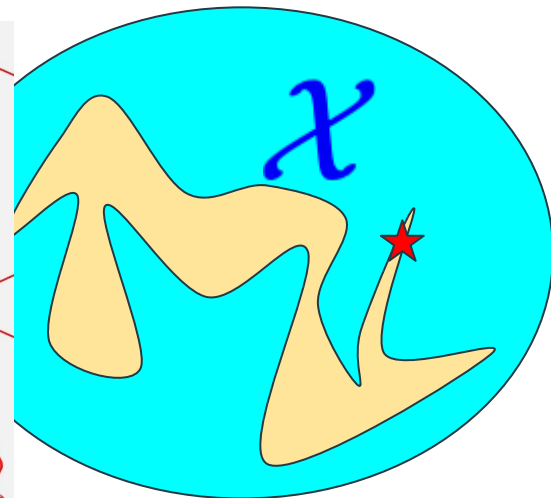
Standard BO

v.s.

BO with GenAI prior



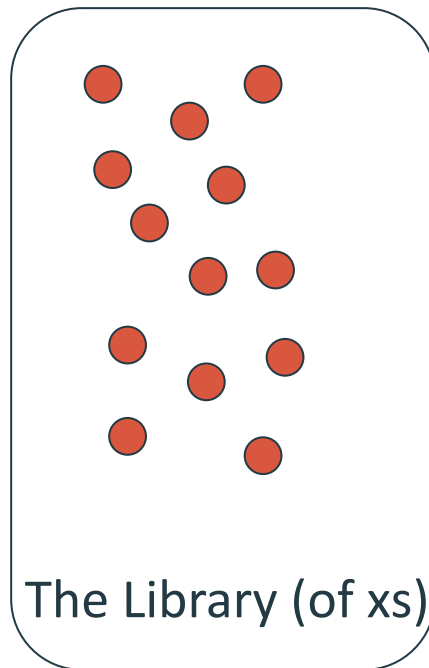
$$\max_{x \in \mathcal{X}} f(x) \\ : P(C(x) = 0) > t$$



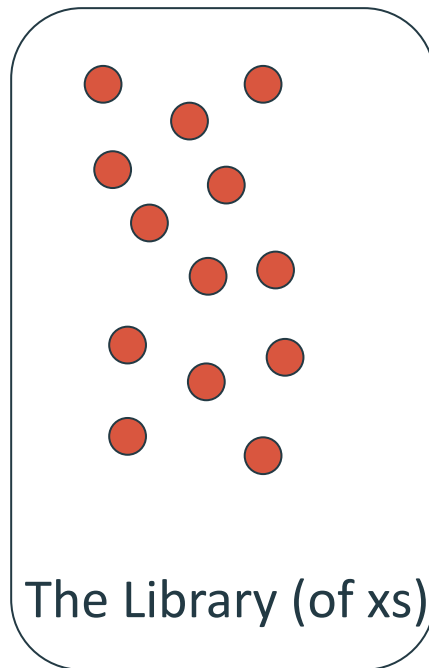
$$\max_{x \in \mathcal{X}} f(x) \\ : P(\dot{x}) > t$$

Eh?

BO over libraries of structures

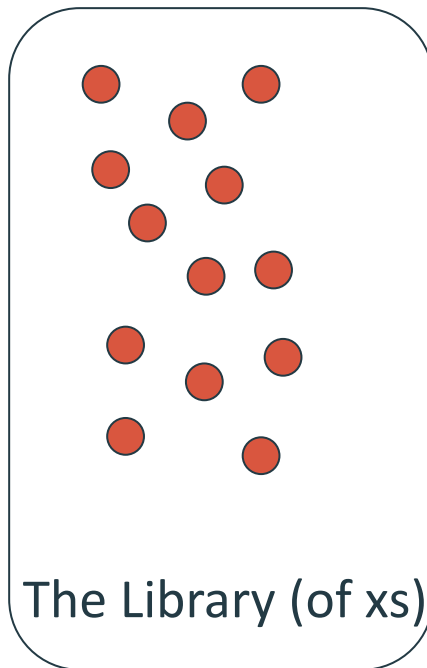


BO over libraries of structures



The Chooser (BO)

BO over libraries of structures

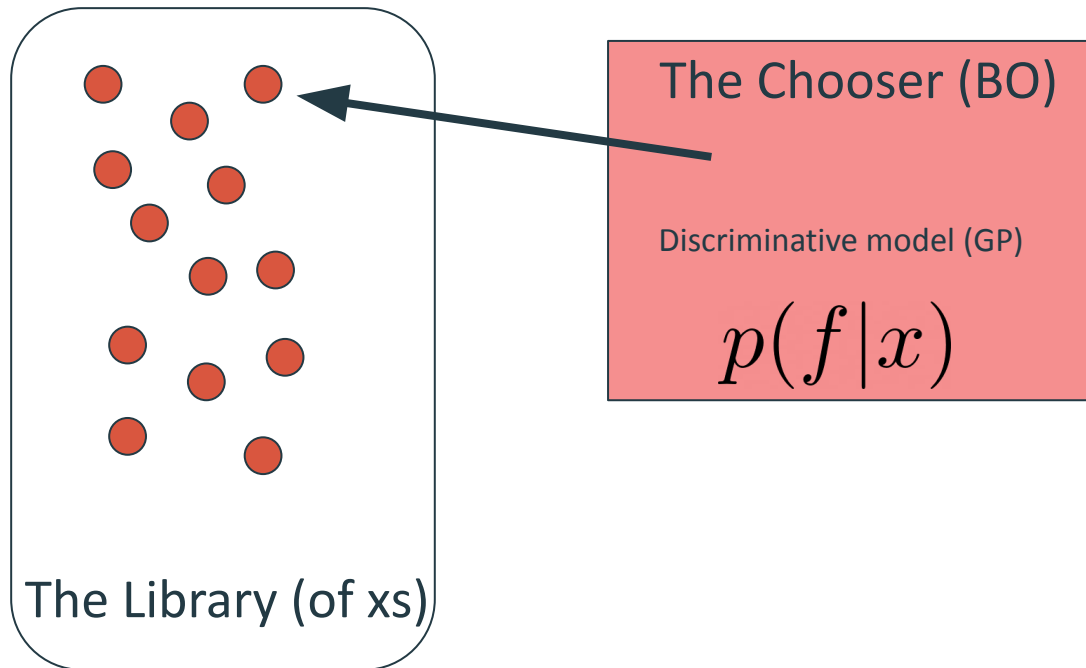


The Chooser (BO)

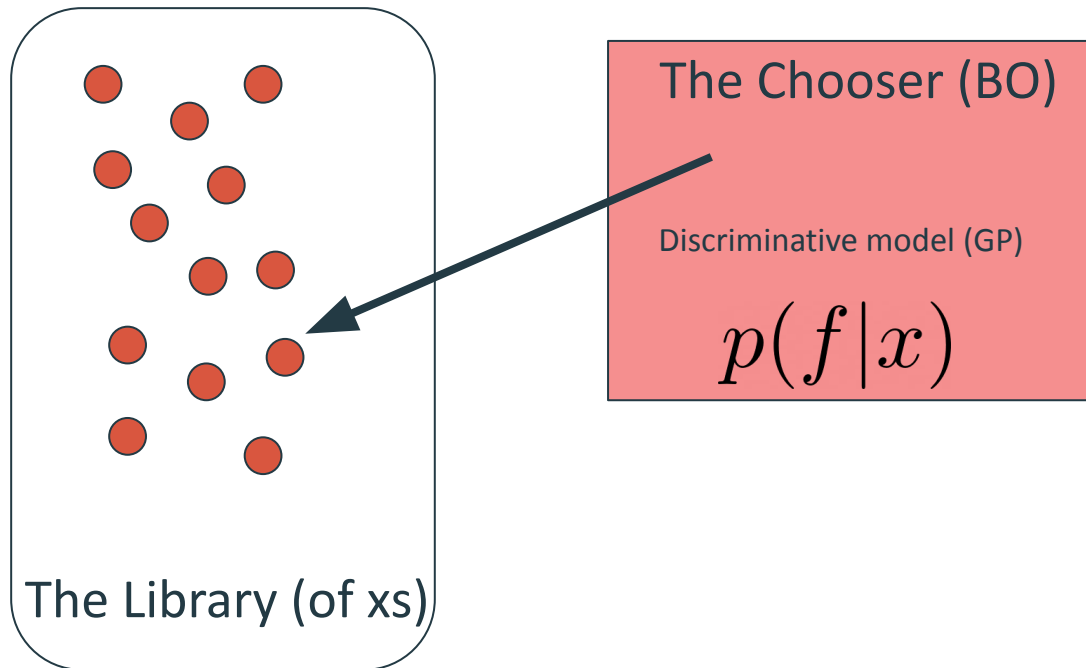
Discriminative model (GP)

$$p(f|x)$$

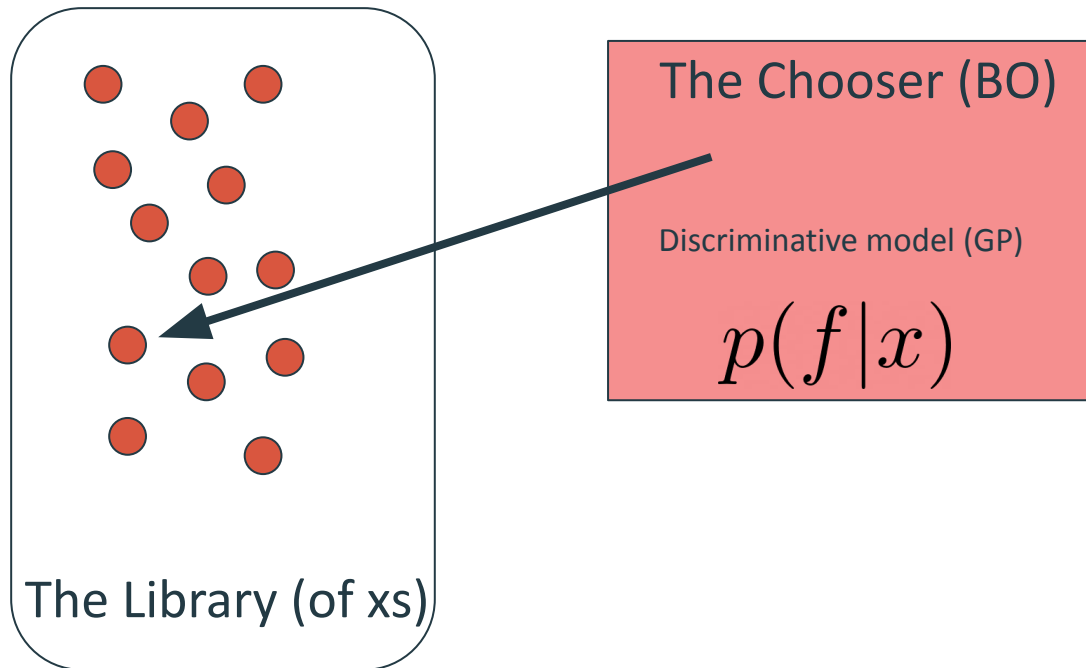
BO over libraries of structures



BO over libraries of structures



BO over libraries of structures



BO over “highly structured” spaces

Can we use $\mathbb{P}(\mathbf{x})$???

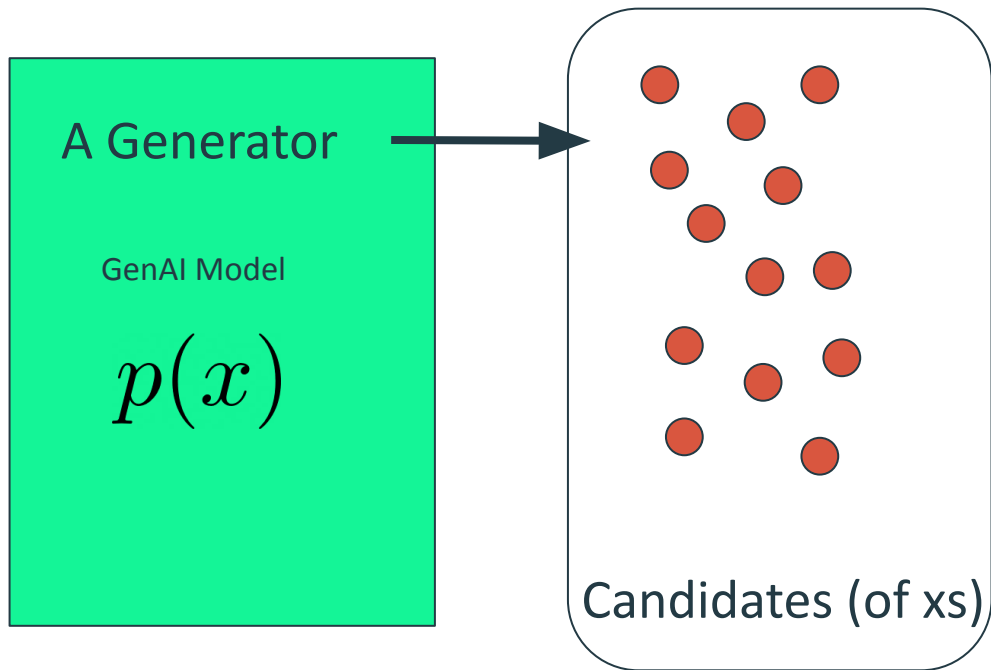
A Generator

GenAI Model

$$p(x)$$

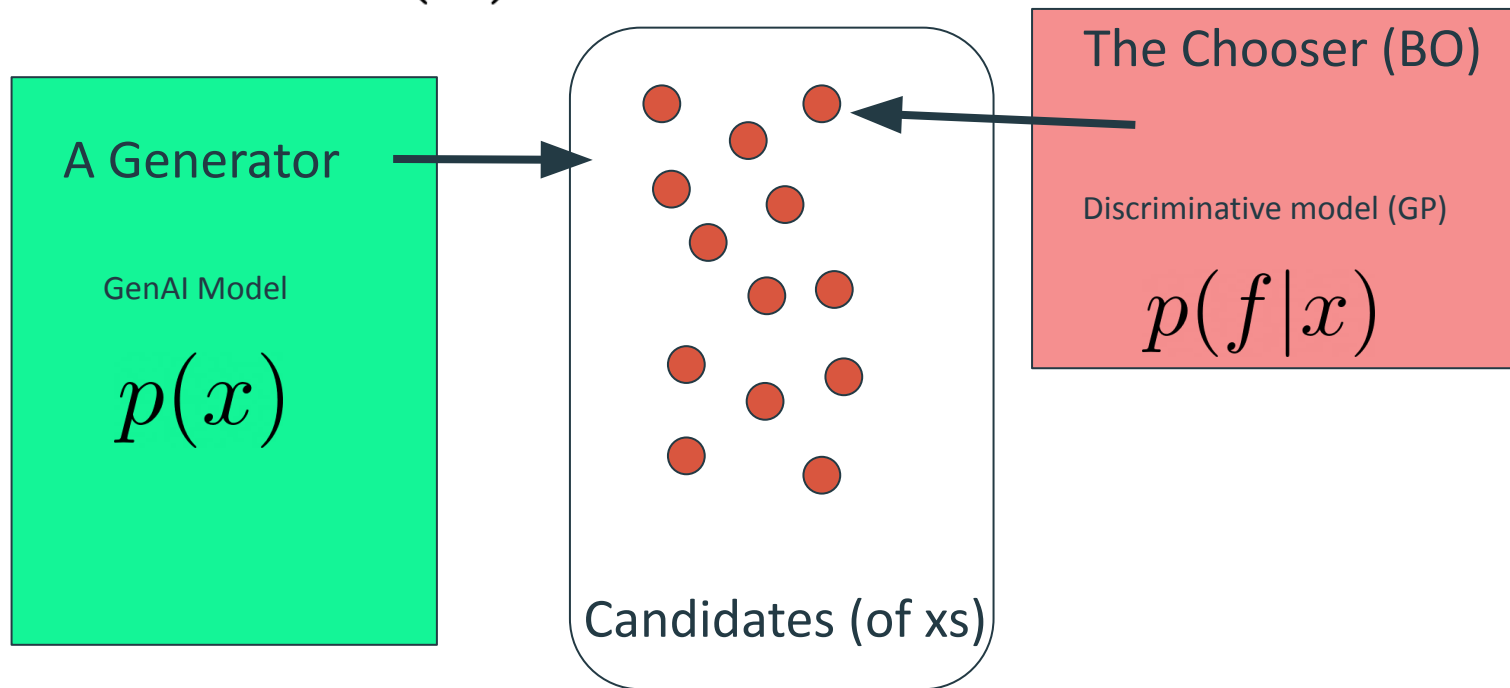
BO over “highly structured” spaces

Can we use $\mathbb{P}(\mathbf{x})$???



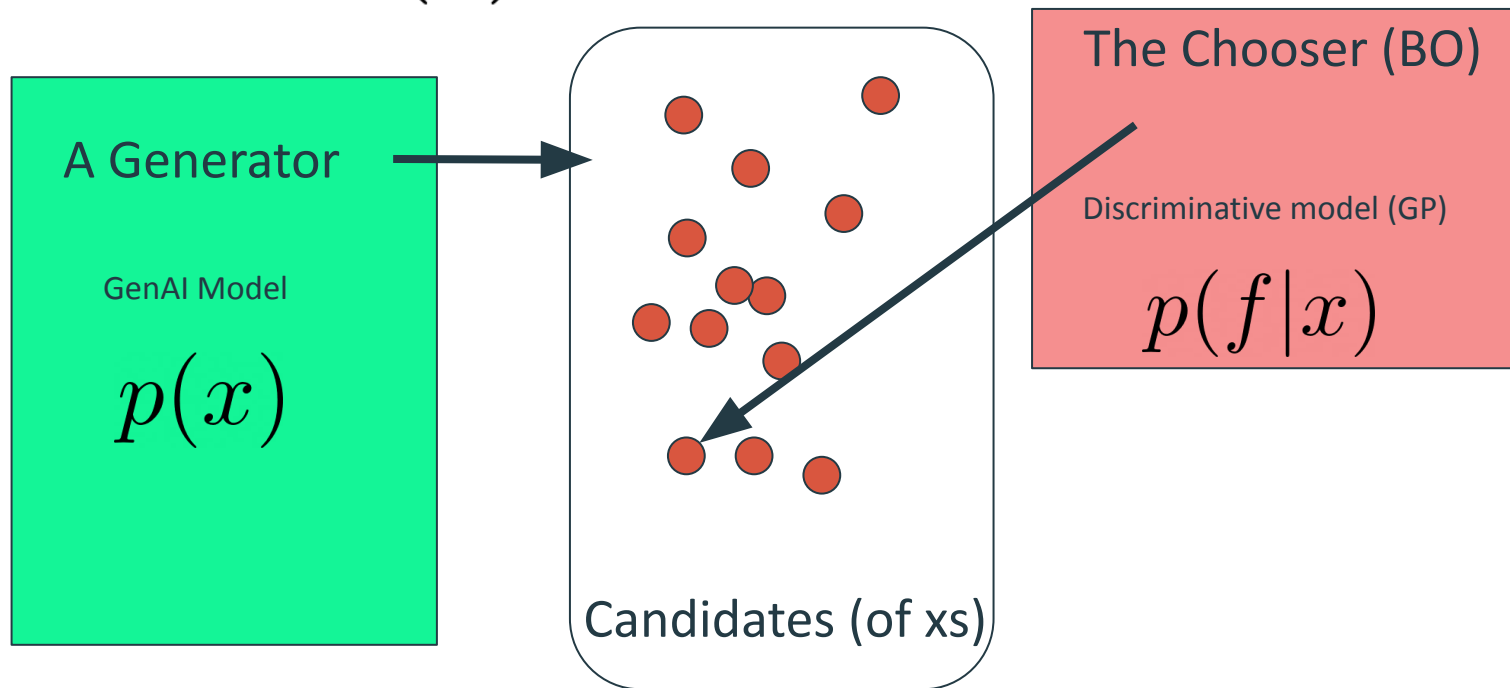
BO over “highly structured” spaces

Can we use $\mathbb{P}(\mathbf{x})$???



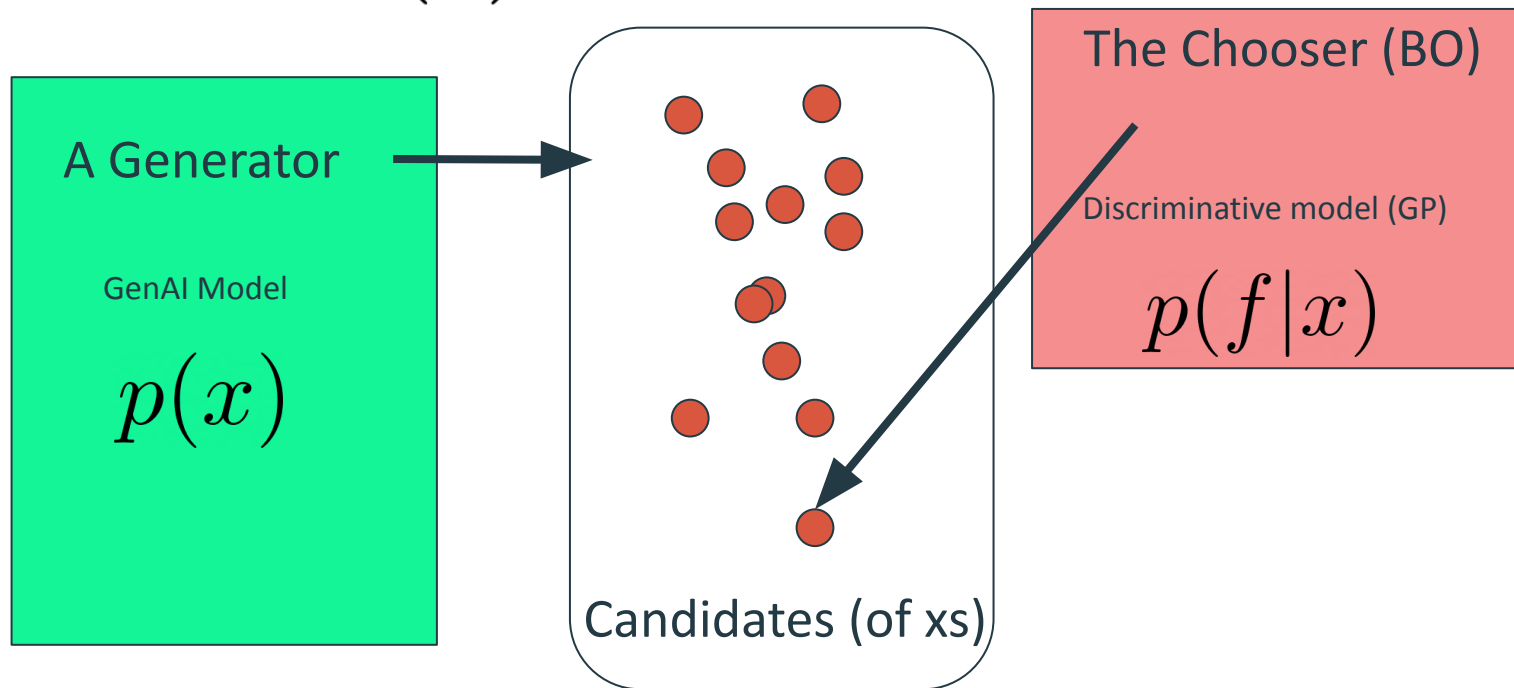
BO over “highly structured” spaces

Can we use $\mathbb{P}(\mathbf{x})$???



BO over “highly structured” spaces

Can we use $\mathbb{P}(\mathbf{x})$???



GenAI is built for sampling

Initial design: $\mathbf{x}_0 \sim p(\mathbf{x})$

GenAI is built for sampling: BO?

Initial design: $\mathbf{x}_0 \sim p(\mathbf{x})$

BO steps: $\mathbf{x}_N \sim p(\mathbf{x} | f_{\mathbf{x}} > f^*, D_N)$



Pol from GP

GenAI is built for sampling: BO?

Initial design: $\mathbf{x}_0 \sim p(\mathbf{x})$

BO steps: $\mathbf{x}_N \sim p(\mathbf{x} | f_{\mathbf{x}} > f^*, D_N)$

- Sampling not optimising
- Model over \mathcal{X} (or \mathcal{Z})



Pol from GP

How do we “condition” GenAI models?

- Train conditional model (expensive, requires specificity)
- Fine-tuning on the fly (still expensive / fragile)
- Model-specific (e.g. guidance for flow-matching)
- **MCMC (???)**
- **Mess around with latents (exploit locality)**

Jamiroquai

🌐 45 languages ▾

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From Wikipedia, the free encyclopedia



Jamiroquai (/dʒəˈmiːrəkwaɪ/ [ⓘ] *je-MIRR-ə-kwy*) are an English [acid jazz](#) and [funk](#) band from London. Formed in 1992, they are fronted by vocalist [Jay Kay](#), and were prominent in the London-based funk and acid jazz movement of the 1990s. They built on their acid jazz sound in their early releases and later drew from [rock](#), [disco](#), [electronic](#) and [Latin music](#) genres. Lyrically, the group have addressed [social](#) and [environmental justice](#). Kay has remained the only constant member through several line-up changes.

The band made their debut under [Acid Jazz Records](#) but subsequently found mainstream success under [Sony](#). While under this label, three of their albums have



The Return of the Space Cowboy

Article [Talk](#)

From Wikipedia, the free encyclopedia

The Return of the Space Cowboy is the second album by English [funk](#) and [acid jazz](#) band [Jamiroquai](#). The album was released on 17 October 1994 under [Sony Soho](#)

Anyone?

Return of the latent space COWBOYS

Categorical Optimisation With Belief Of
underlYing Smoothness

Henry Moss,
Sebastian Ober,

Tom Diethe, Head of the Centre for AI, Data Science & AI, Biopharma R&D, AstraZeneca, Cambridge, UK



VAEs are built for sampling

Initial design: $\mathbf{x}_0 \sim p(\mathbf{x})$

VAEs are built for sampling

Initial design: $\mathbf{x}_0 \sim p(\mathbf{x})$

COWBOYS chooses: $\mathbf{x}_N \sim p(\mathbf{x} | f_{\mathbf{x}} > f^*, D_N)$

VAEs are built for sampling

Initial design: $\mathbf{x}_0 \sim p(\mathbf{x})$

COWBOYS chooses: $\mathbf{x}_N \sim p(\mathbf{x} | f_{\mathbf{x}} > f^*, D_N)$

- Sampling not optimising
- Tanimoto Model over \mathcal{X}

VAEs are built for sampling

Initial design: $\mathbf{x}_0 \sim p(\mathbf{x})$

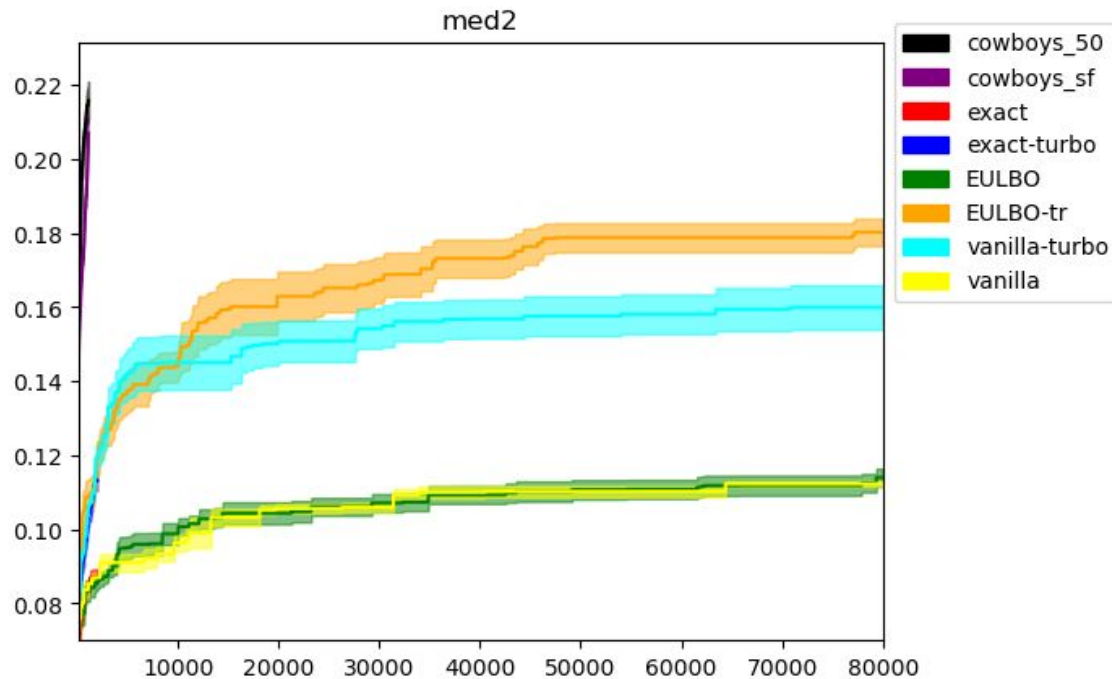
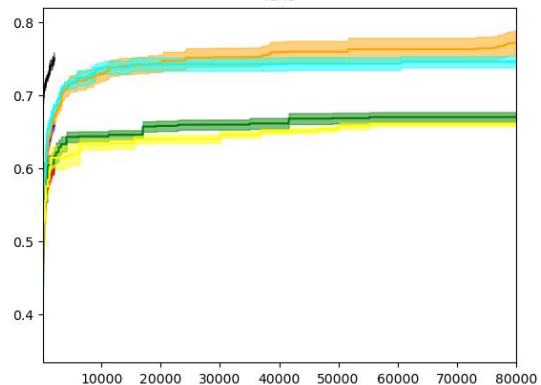
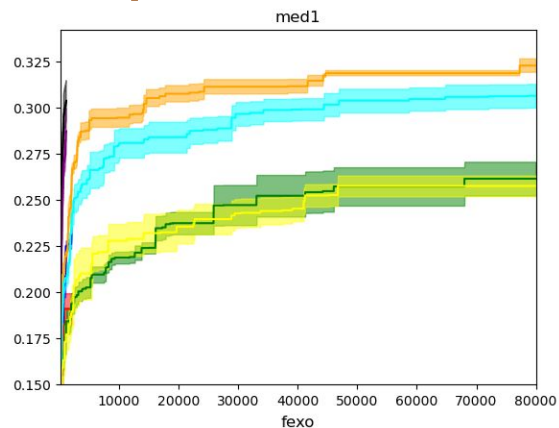
COWBOYS chooses: $\mathbf{x}_N \sim p(\mathbf{x} | f_{\mathbf{x}} > f^*, D_N)$

- Sampling not optimising
- Tanimoto Model over χ

So use MCMC:

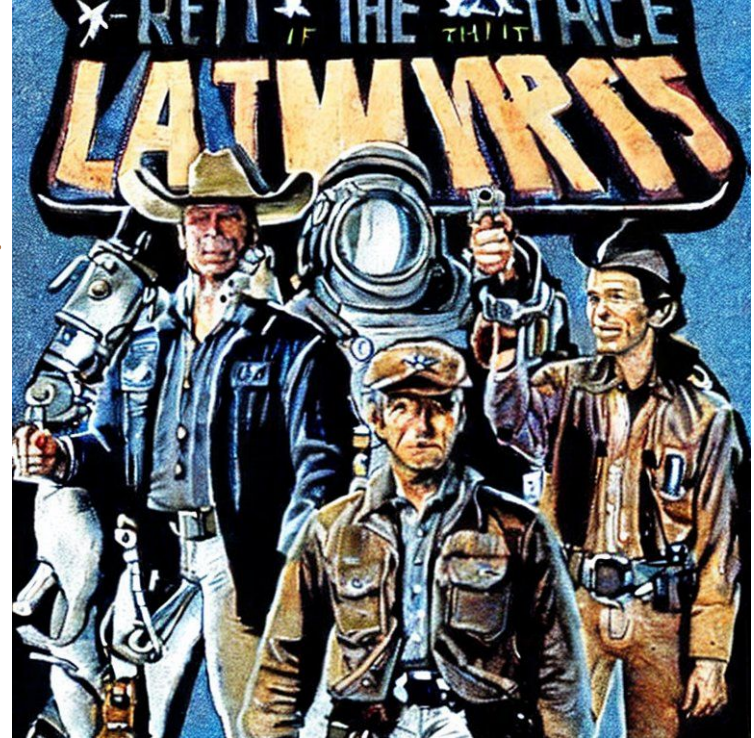
1. Pre-conditioned Crank Nicolson
2. Parallel Tempering

Toy Problem: Guacamole Molecule Opt



ICML 2025

- Sample, don't optimize
- Beware of the geometry of latent spaces
- Still loads to do here!

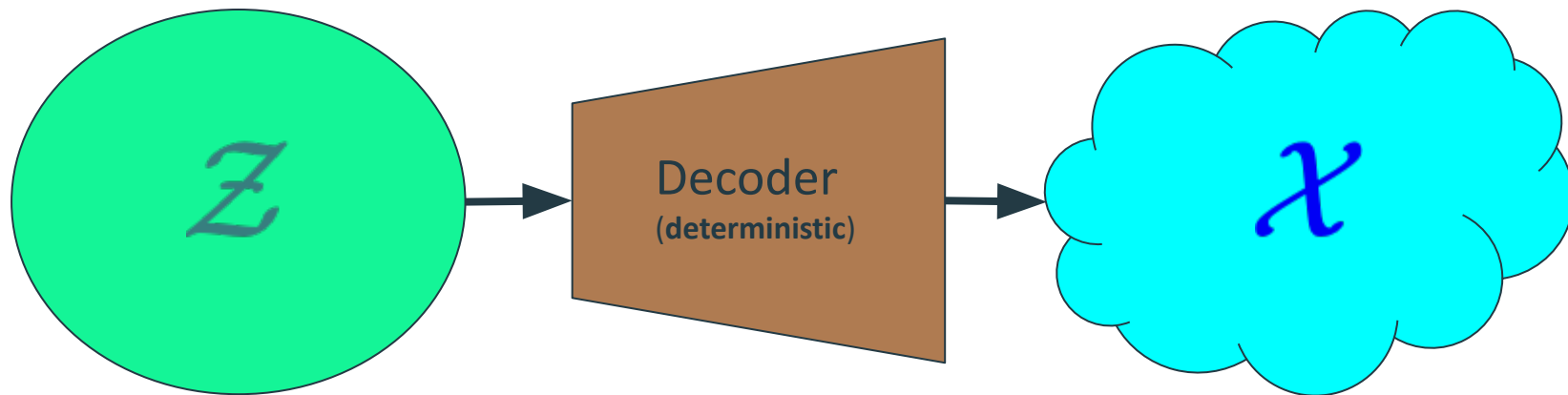


Linear combinations of Latents in Generative Models: Subspaces and Beyond

Erik Bodin
Carl Henrik Ek
Henry Moss



Priors over “Highly Structured” spaces

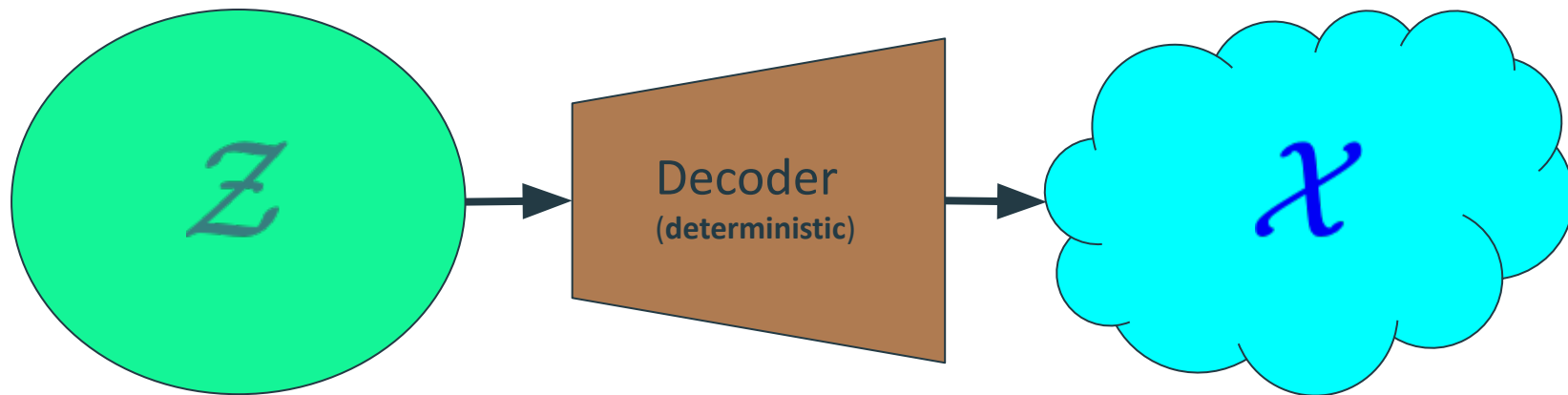


$$\mathbb{P}(\mathbf{z}) = \mathcal{N}_d(\mathbf{0}, I_d)$$

$$\mathbb{P}(\mathbf{x}) = ???$$

Diffusion / Flow matching e.t.c ($d \gg 10_000$)

Priors over “Highly Structured” spaces



$$\mathbb{P}(\mathbf{z}) = \mathcal{N}_d(\mathbf{0}, I_d)$$

$$\mathbb{P}(\mathbf{x}) = ???$$

Only give the model what it
is trained to expect!

An aside: **typical** Gaussian samples

Theorem 2 (Gaussian Annulus Theorem). *The Gaussian Annulus Theorem states, that nearly all the probability of a spherical Gaussian with unit variance is concentrated in a thin annulus of width $O(1)$ at radius \sqrt{d} .*

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{0}, I_d) \Rightarrow |\mathbf{z}|^2 \sim \chi^2(d)$$

Common “latent space manipulations”

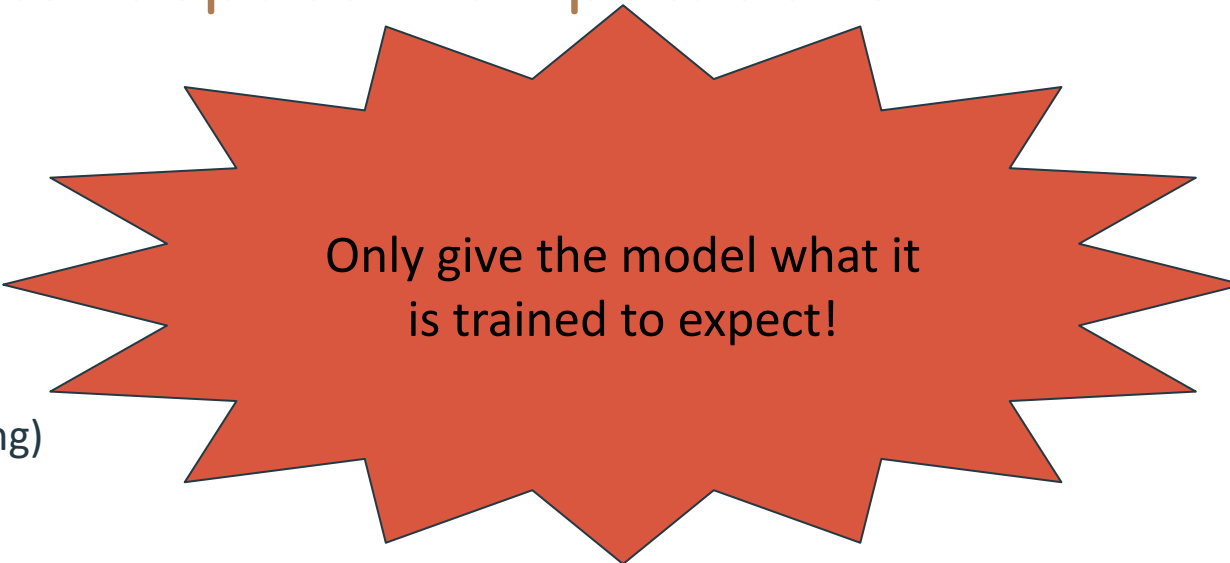
- Interpolation
- Addition
- Centroids (averaging)

Common “latent space manipulations”

- Interpolation
- Addition
- Centroids (averaging)
- **Subspaces!**

Common “latent space manipulations”

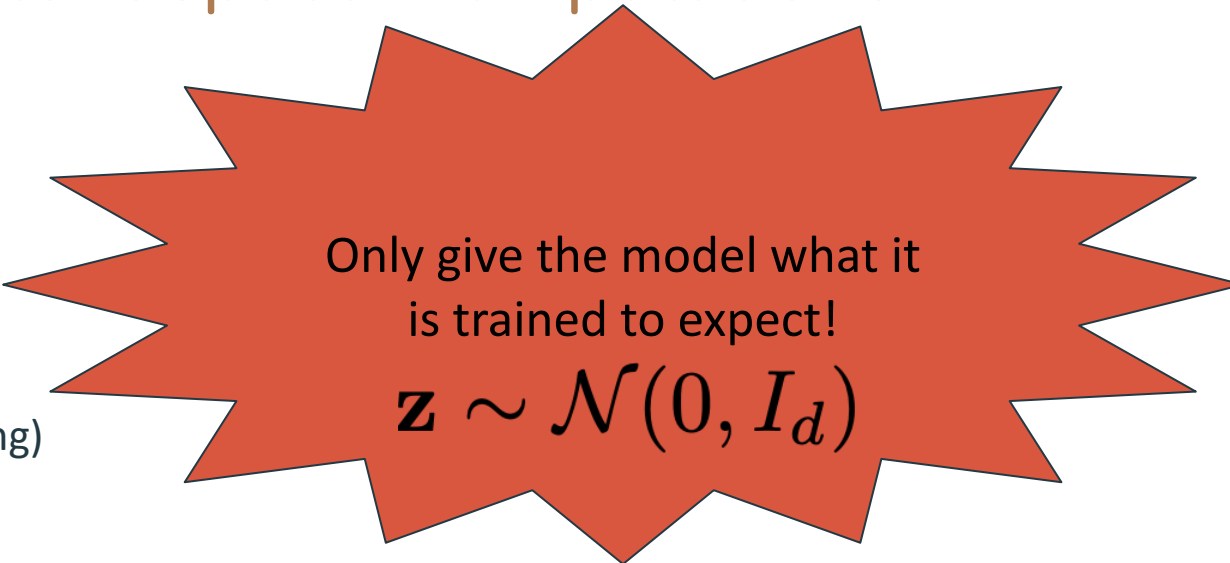
- Interpolation
- Addition
- Centroids (averaging)
- **Subspaces!**



Only give the model what it
is trained to expect!

Common “latent space manipulations”

- Interpolation
- Addition
- Centroids (averaging)
- **Subspaces!**

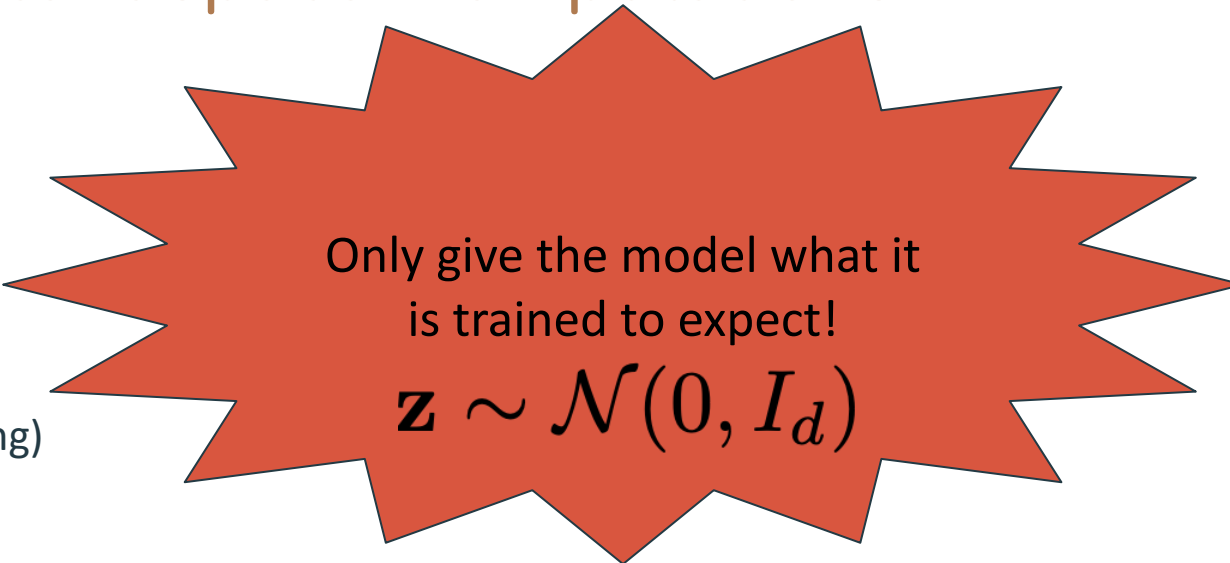


Only give the model what it
is trained to expect!

$$\mathbf{z} \sim \mathcal{N}(0, I_d)$$

Common “latent space manipulations”

- Interpolation
- Addition
- Centroids (averaging)
- **Subspaces!**

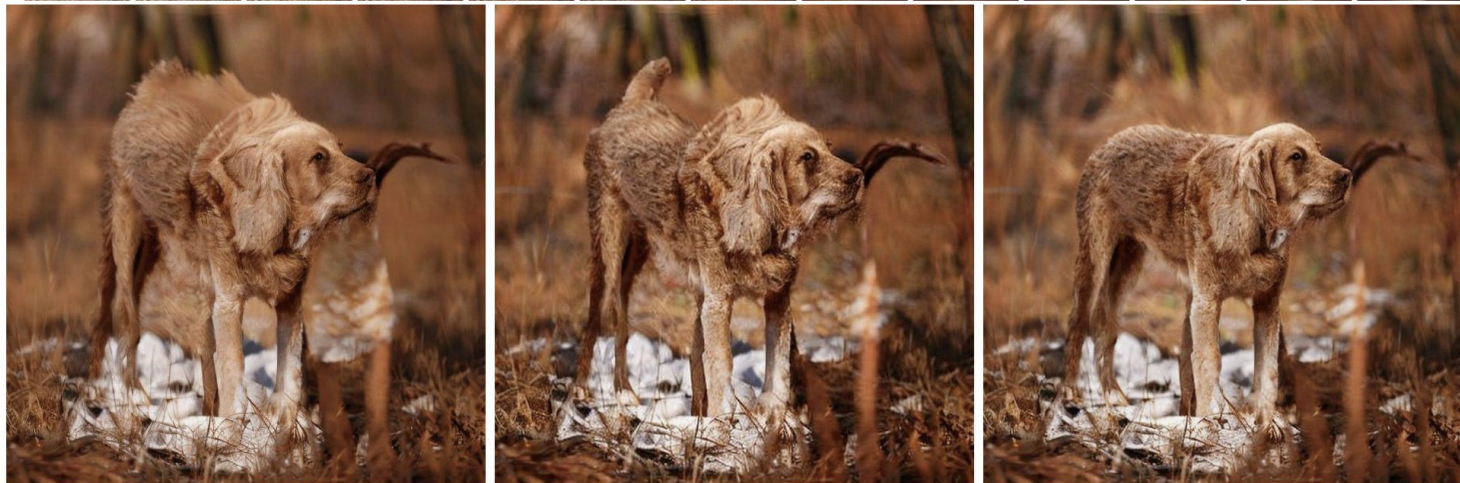
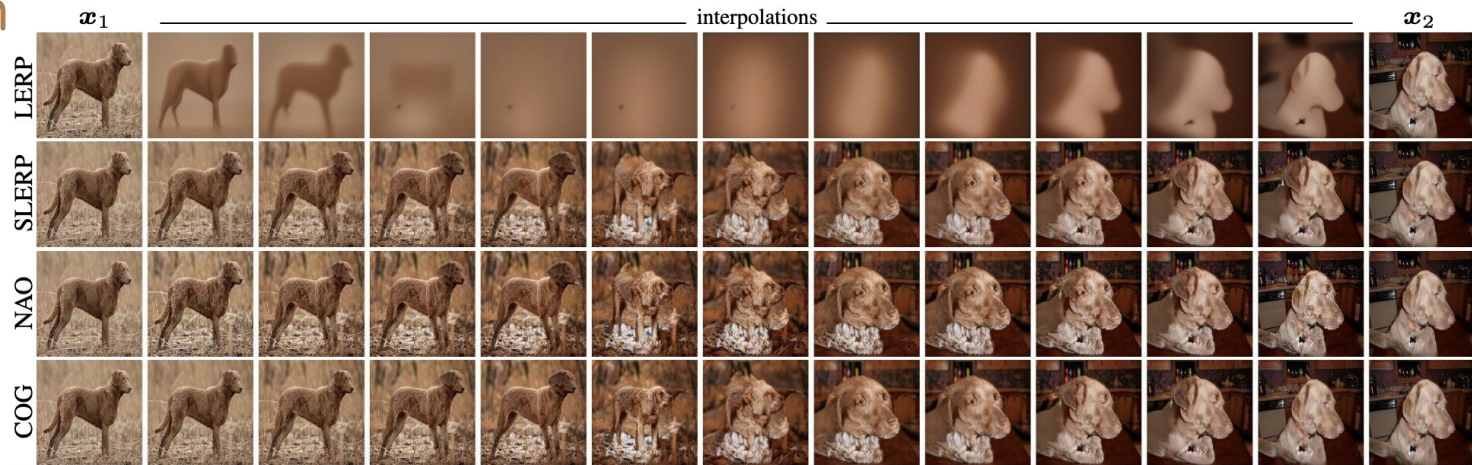


Only give the model what it
is trained to expect!

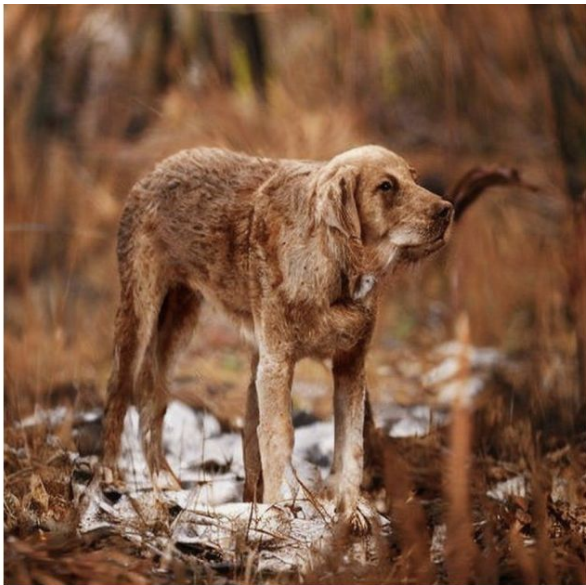
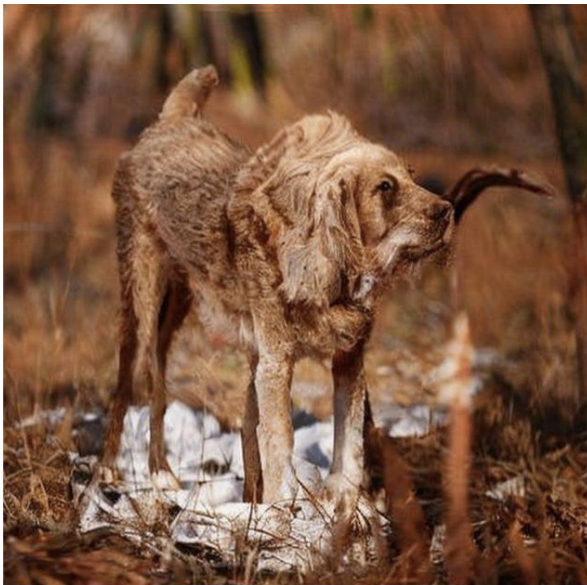
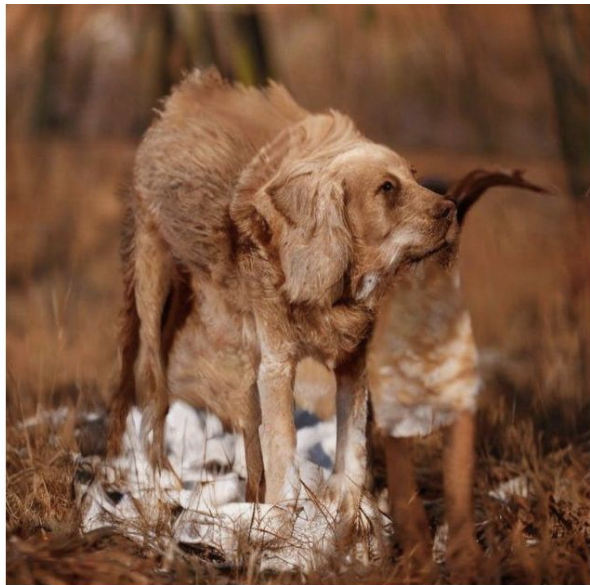
$$\mathbf{z} \sim \mathcal{N}(0, I_d)$$

COG: LINEAR COMBINATIONS OF GAUSSIAN LATENTS

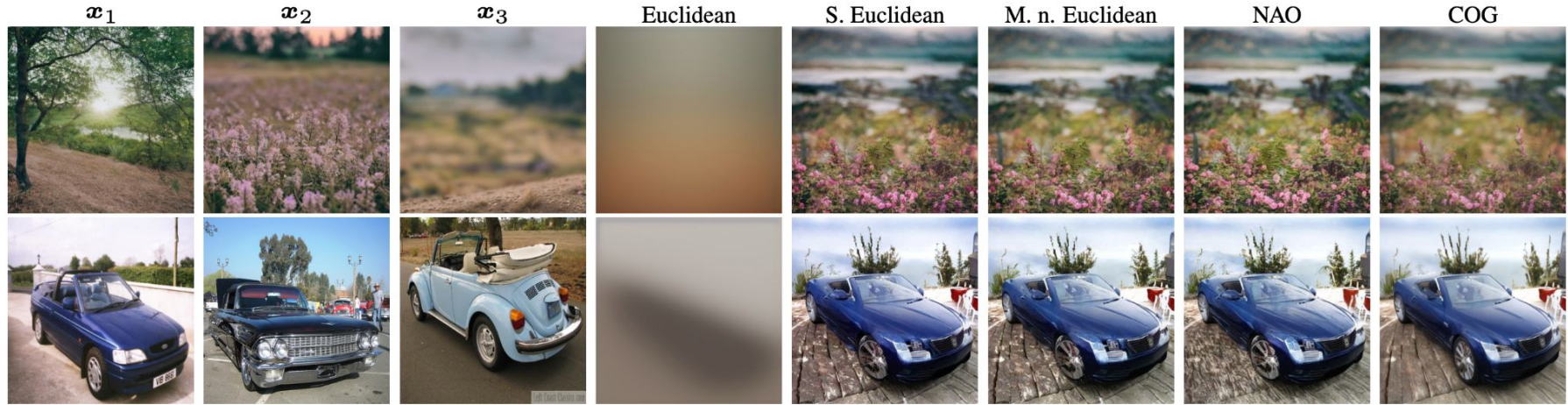
Interpolation



Interpolation



Centroid determination



Centroid determination



Common “latent space manipulations”

$$\mathbf{y} := \sum_{k=1}^K w_k \mathbf{x}_k = \mathbf{w}^T \mathbf{X},$$

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- Centroids: $\mathbf{y} = \mathbf{w}^T \mathbf{X}$, where $\mathbf{w} = [\frac{1}{K}]^K$, and $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_K]$.

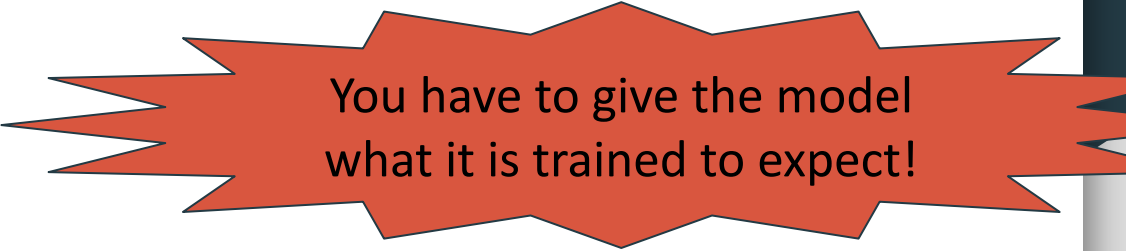
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- Subspace projections:

$$\mathbf{y} = s(\mathbf{x}) = \mathbf{U}\mathbf{U}^T \mathbf{x} = \mathbf{U}\mathbf{h}$$

LOL: Linear combinations Of Latents

A red, jagged speech bubble with a black outline, pointing towards the right. It contains the text "You have to give the model what it is trained to expect!".

You have to give the model
what it is trained to expect!

LOL: Linear combinations Of Latents

$$\mathbf{y} := \sum_{k=1}^K w_k \mathbf{x}_k = \mathbf{w}^T \mathbf{X},$$

You have to give the model what it is trained to expect!

Instead decode $\mathbf{z} = \frac{\mathbf{y}}{\sqrt{(\beta)}} \sim \mathcal{N}(0, I) \quad \beta = \sum_{k=1}^K w_k^2.$

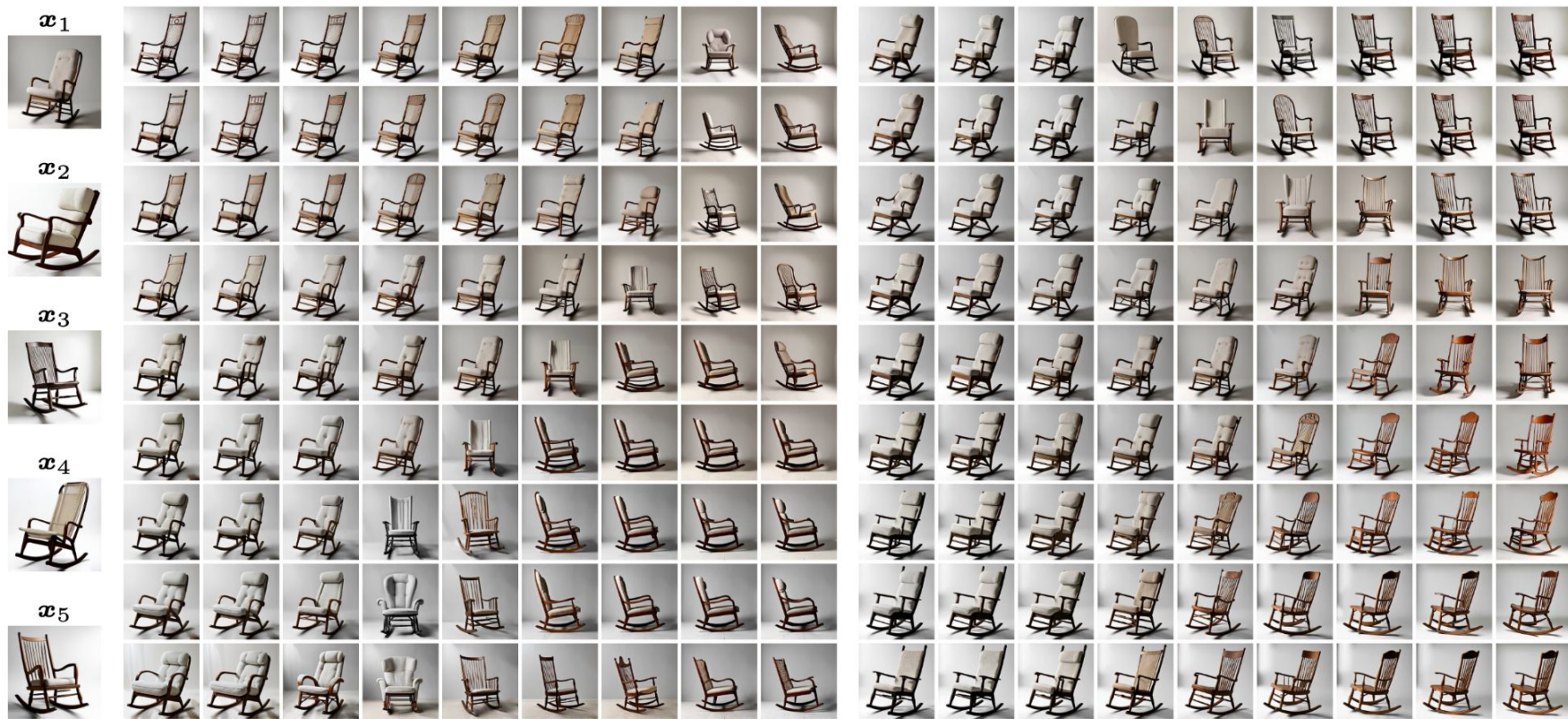
Low-dimensional (searchable) subspaces without LOL



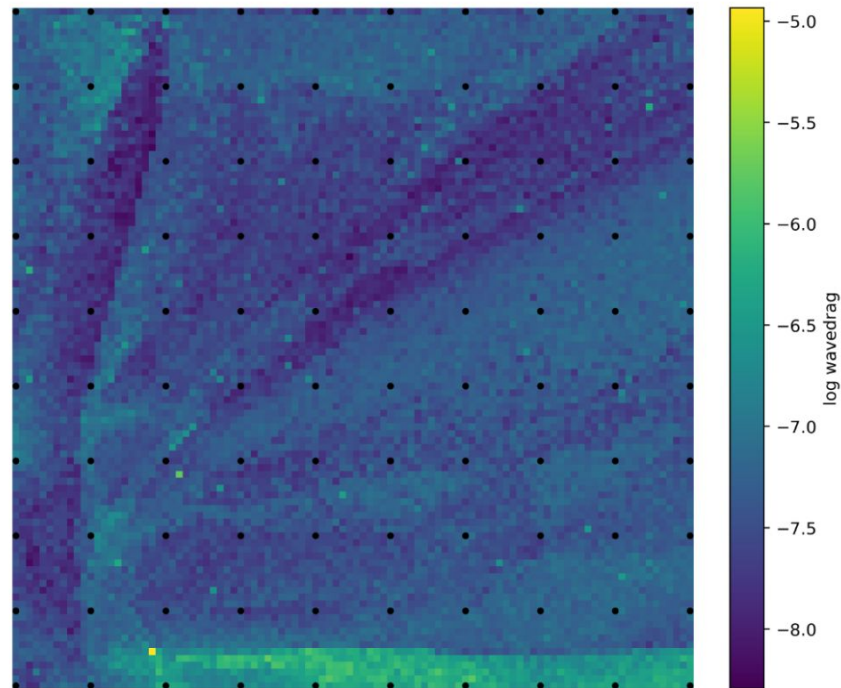
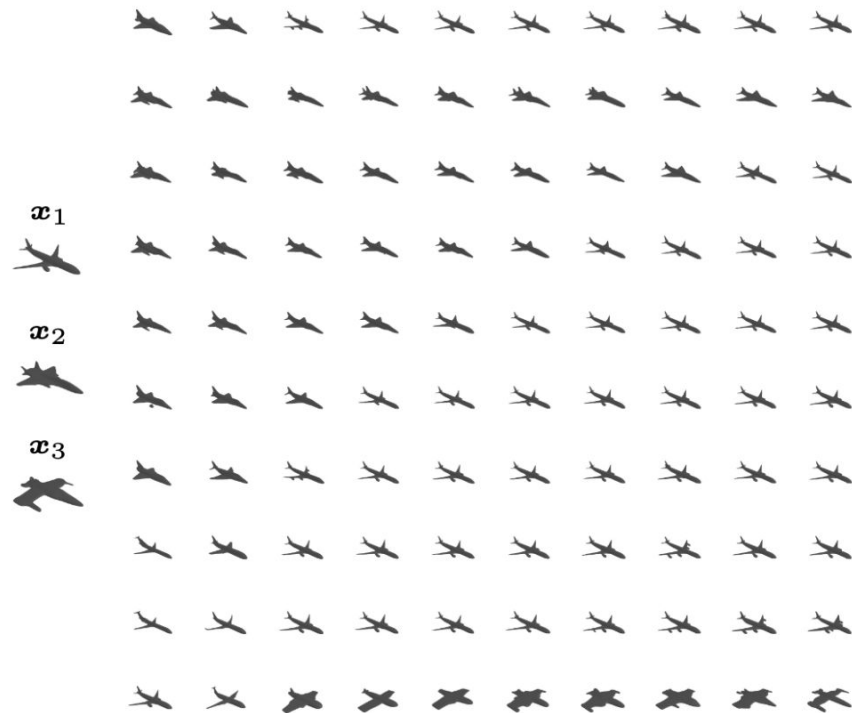
Low-dimensional (searchable) subspaces with LOL



More Low-dimensional (searchable) subspaces



Even more Low-dimensional (searchable) subspaces



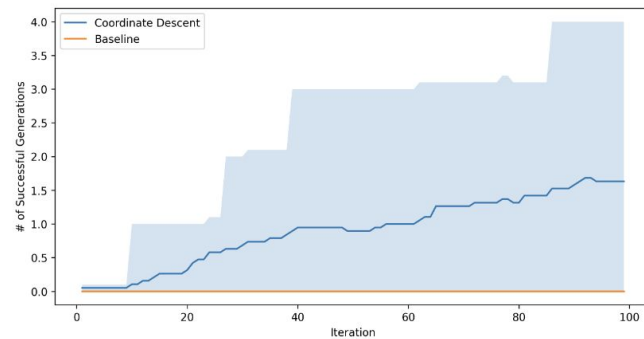
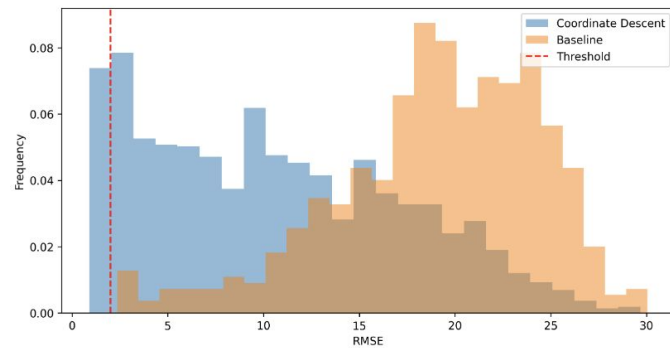
Find long “realistic protein”, using RFDiffusion



RFDiffusion -> ProteinMPNN -> Alphafold

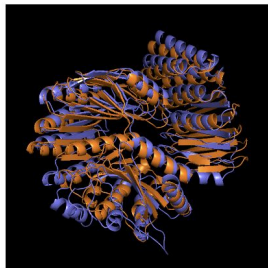


Work in progress: optimisation in latent space of RFdiffusion

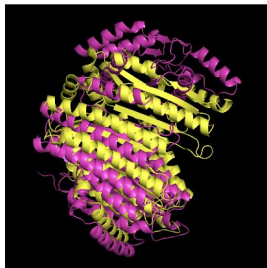




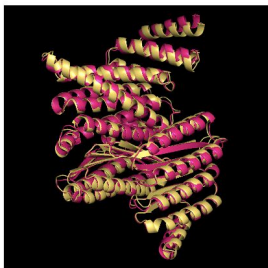
Best random design



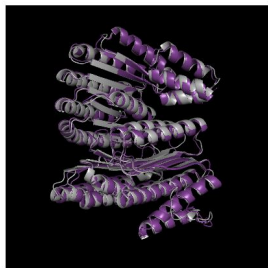
5th best random design



10th best random design



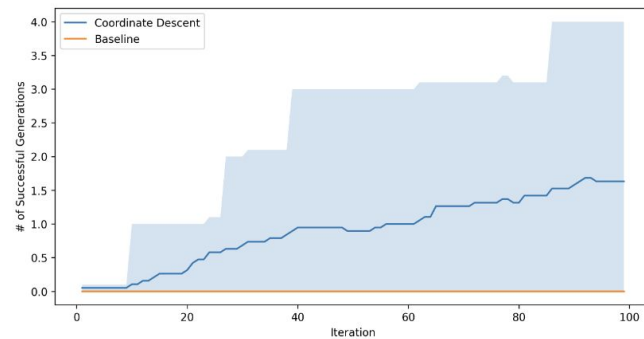
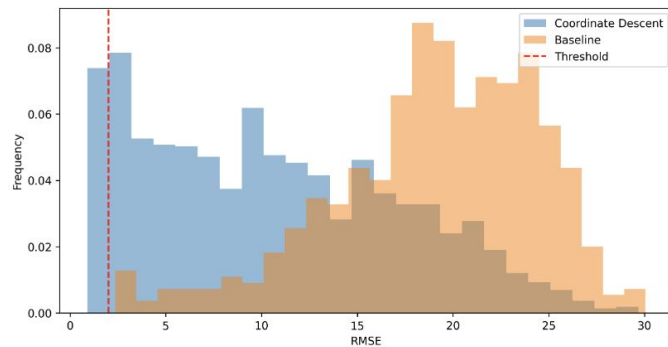
best from coordinate descent



5th best from coordinate descent



10th best from coordinate descent



Work in progress: optimisation in latent space of RFDiffusion

ICLR 2025:

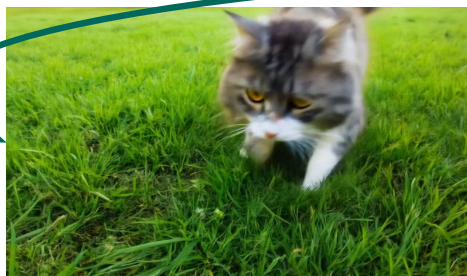
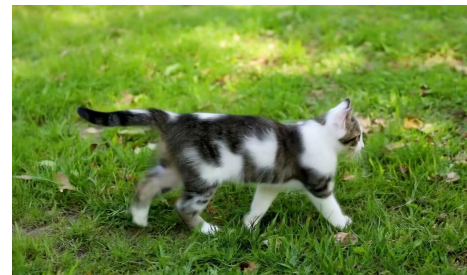
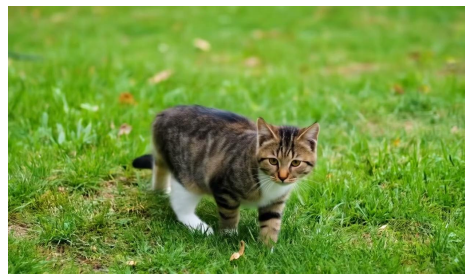
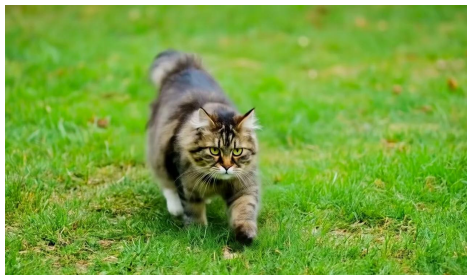
- Perform any linear combination of latents
- More general distributions
- Statistical tests to assert validity of inversions



- Now doing optimisation in these subspaces!

More interpolation (audio and video)

Start Video



End Video

